

Beurteilung und Beeinflussung der Zuverlässigkeit von Tiefziehprozessen in der frühen Entwurfsphase

Stephan Pannier
Wolfgang Graf
Michael Kaliske

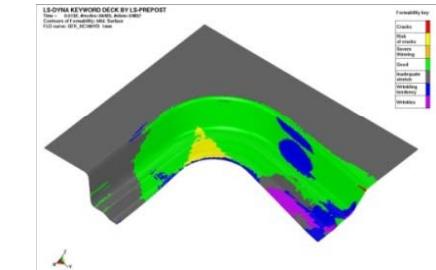
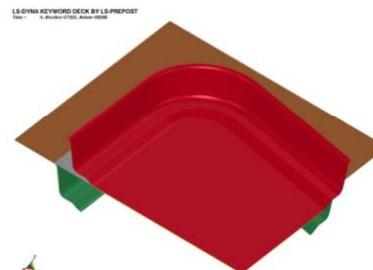
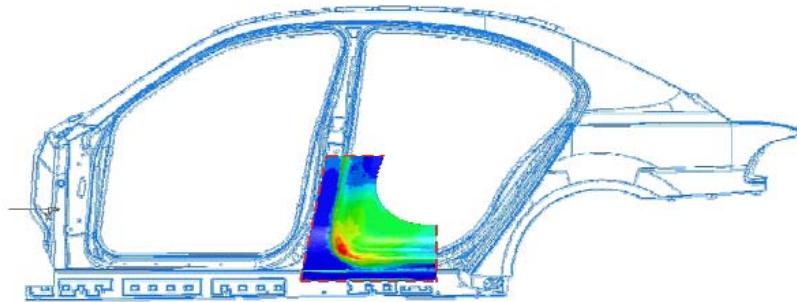
Kathrin Grossenbacher
Markus Ganser
Arnulf Lipp

Martin Liebscher
Heiner Müllerschön

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Motivation



charge A



too many rejects in production process

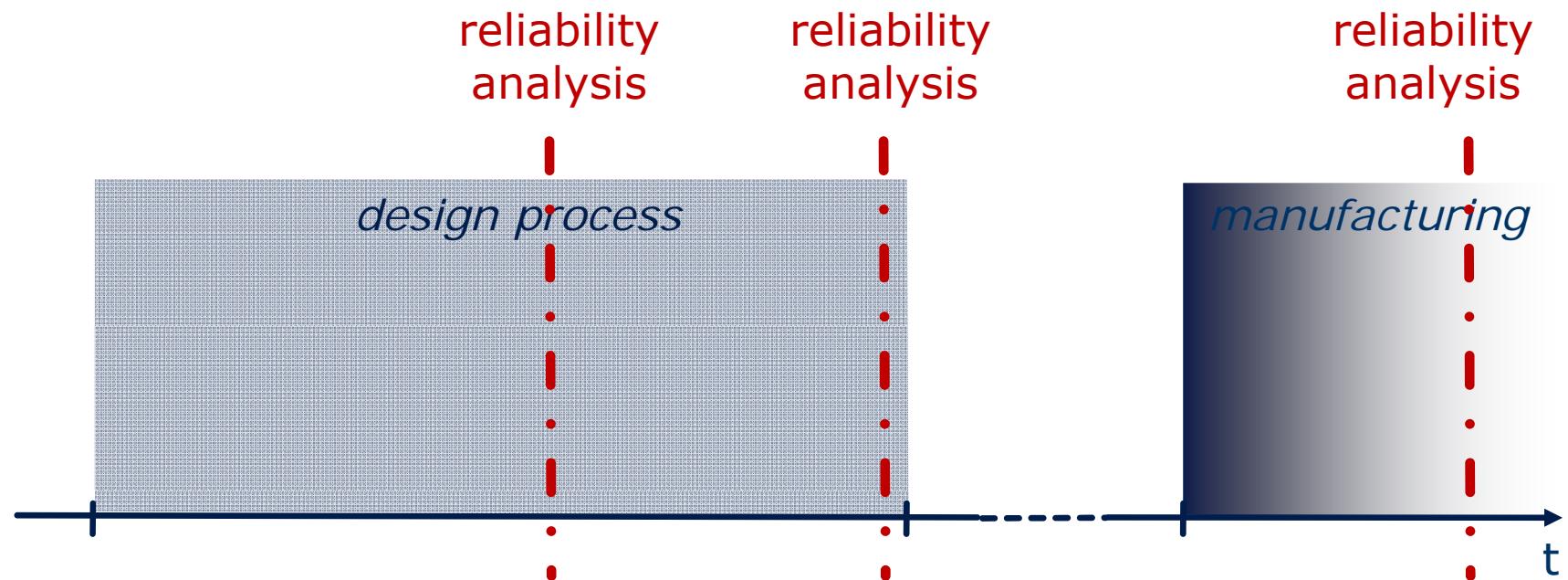
charge B



reliable production process

- numerical verification **afterwards**
- source of trouble - delivery tolerances

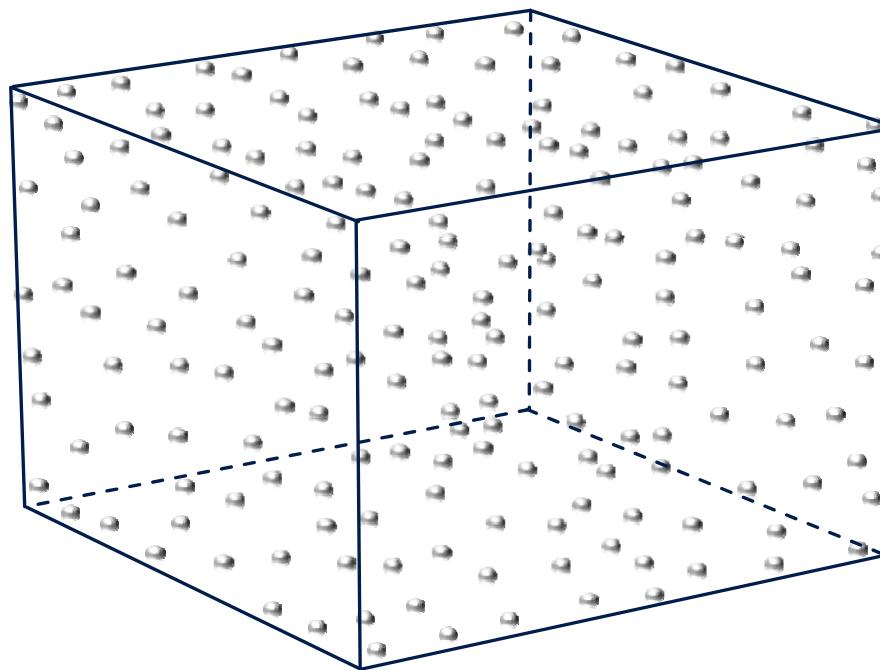
Definition



- reliability analysis in an early design stages
 - modifications of design parameters easier
 - less expensive modifications
- identification of alternative design spaces

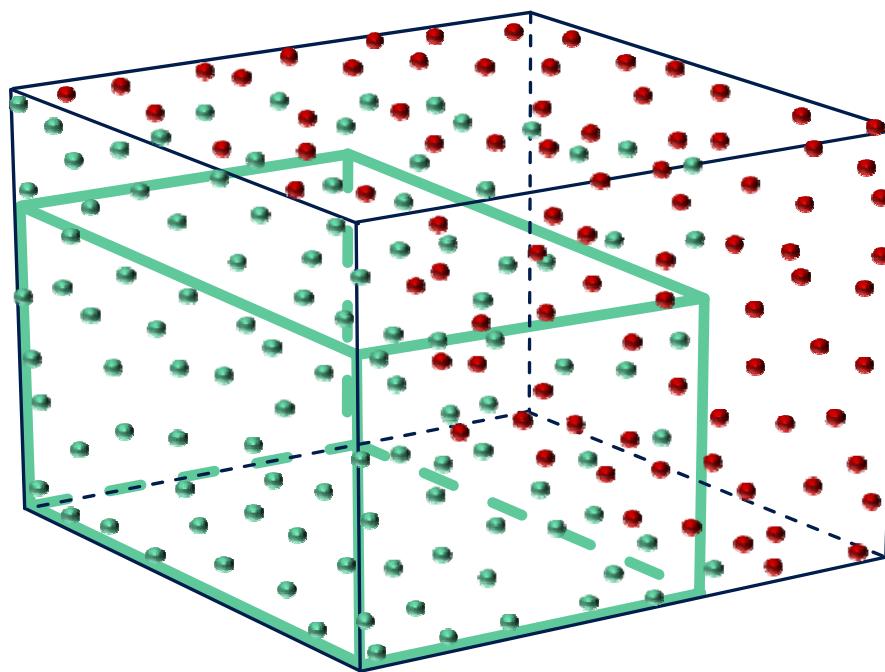
Example

- simple deep drawing example – 3 input quantities, 1 results quantity
- e.g. input: 2 draw bead forces, 1 binder force
result: thinning of blank

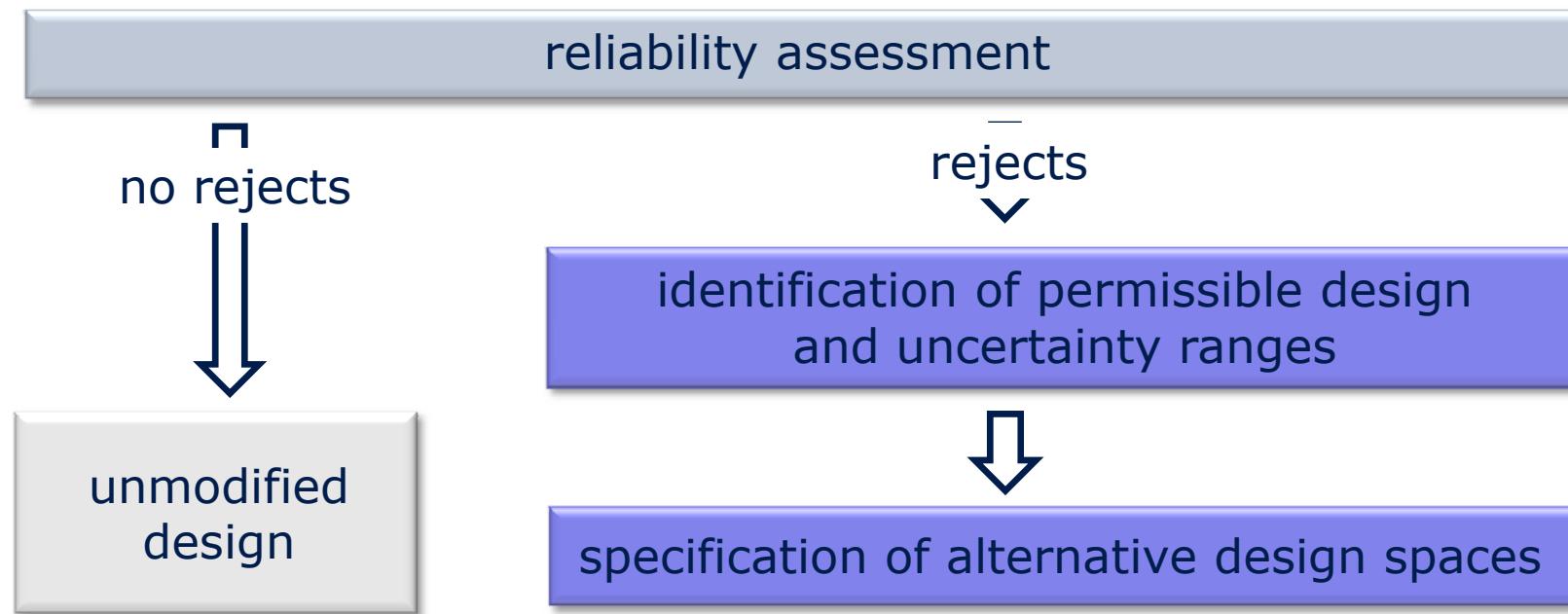


Example

- simple deep drawing example – 3 input quantities, 1 results quantity
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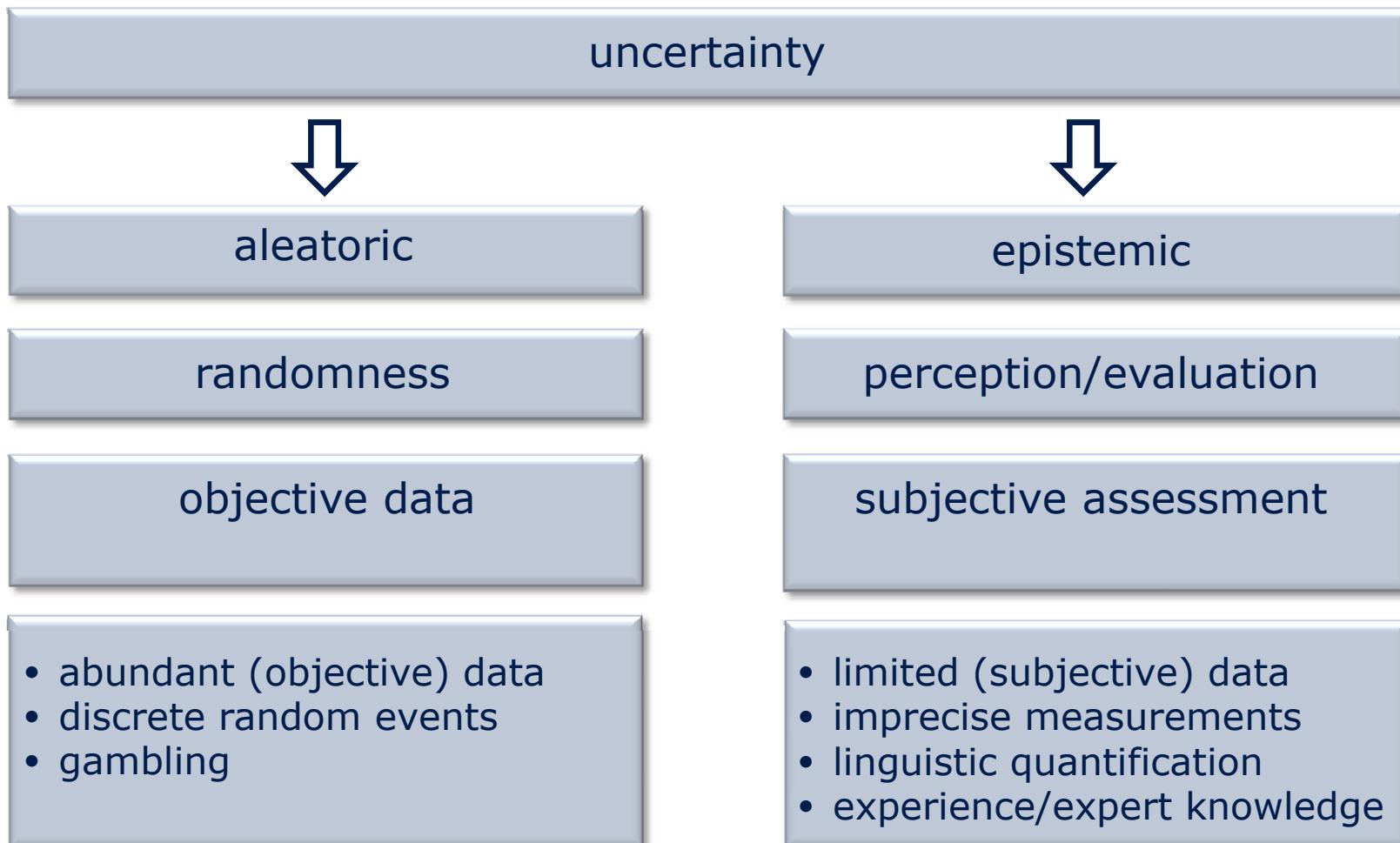
Solution statement



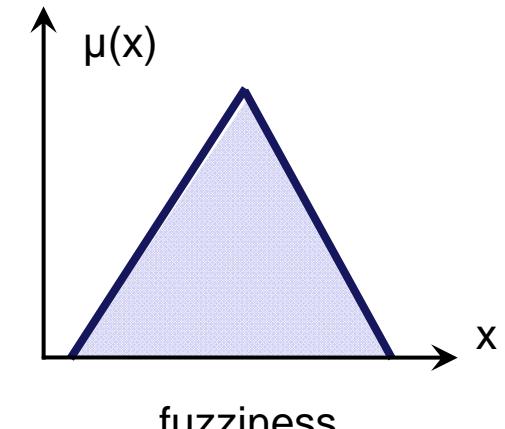
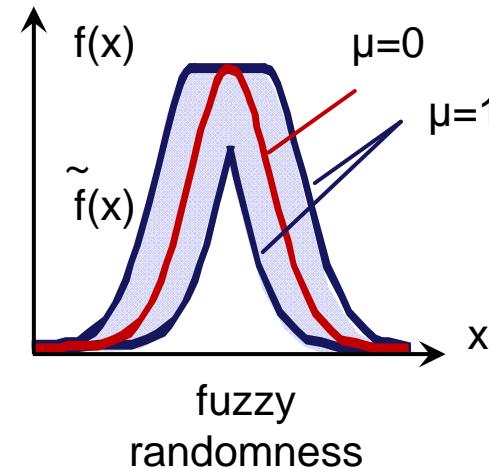
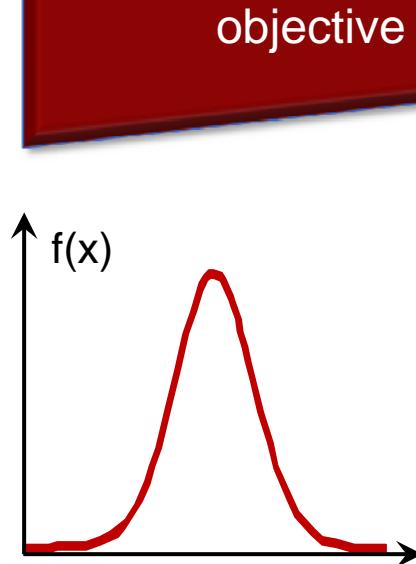
- preconditions
 - rare, vague information about uncertainty ranges
 - arbitrary structural behavior, no one-to-one functions
 - applicability of alternative design ranges in industrial environment

Reliability analysis

Uncertainty modeling

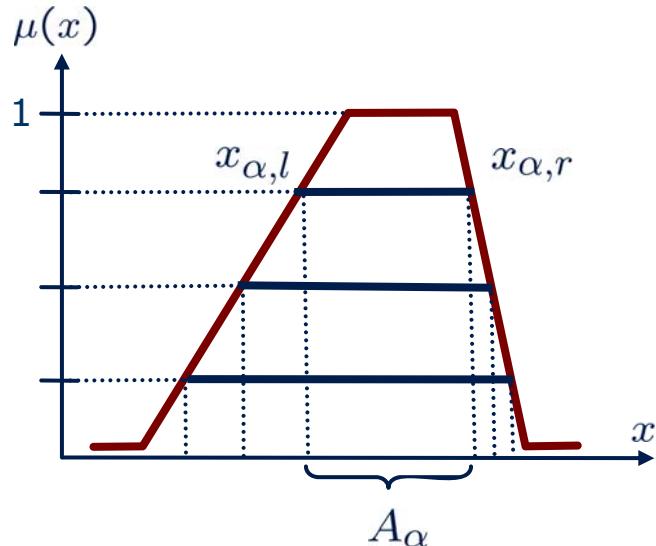


Uncertainty modeling



subjective information

Fuzzy set



- α -level discretization

$$\tilde{A} = (A_\alpha \mid \alpha \in [0, 1])$$

$$A_\alpha = \{x \in \mathbb{R} \mid \mu_{\tilde{A}}(x) \geq \alpha\}$$

$$A_{\alpha_i} \subseteq A_{\alpha_k} \quad \forall \alpha_i \geq \alpha_k$$

- general definition

$$\begin{aligned}\tilde{A} &= \{(x, \mu_{\tilde{A}}(x)) \mid x \in \mathbb{R}, \mu_{\tilde{A}}(x) \in [0, 1]\} \\ \mu_{\tilde{A}} &: \mathbb{R} \rightarrow [0, 1]\end{aligned}$$

- convexity

$$\forall \lambda \in [0, 1], x_1, x_2 \in \mathbb{R} :$$

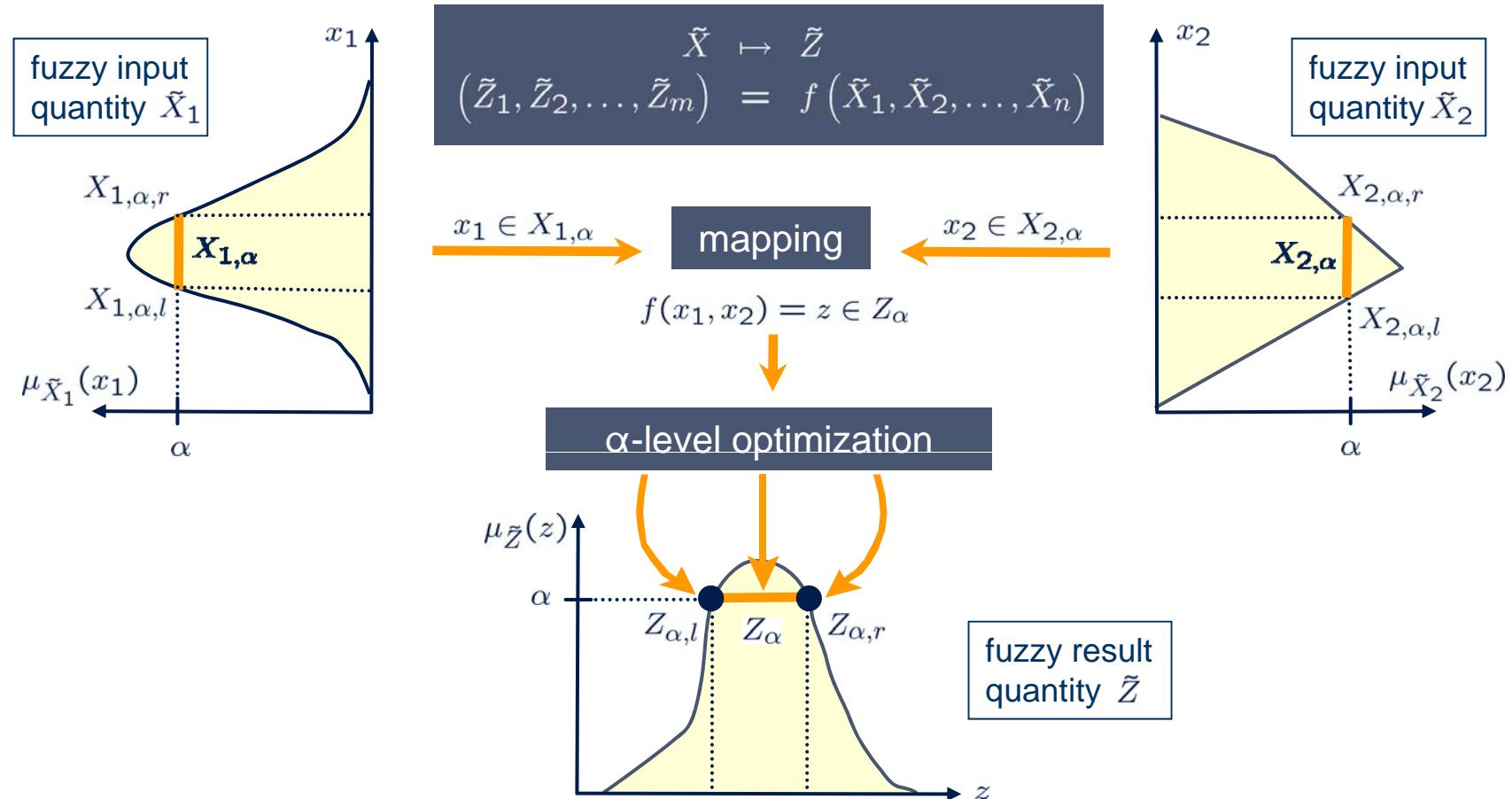
$$\mu_{\tilde{A}}(\lambda x_2 + (1 - \lambda)x_1) \geq \min(\mu_{\tilde{A}}(x_1), \mu_{\tilde{A}}(x_2))$$

- α -level optimization

$$z_{\alpha,l} = \min_{x \in A_\alpha} f(x)$$

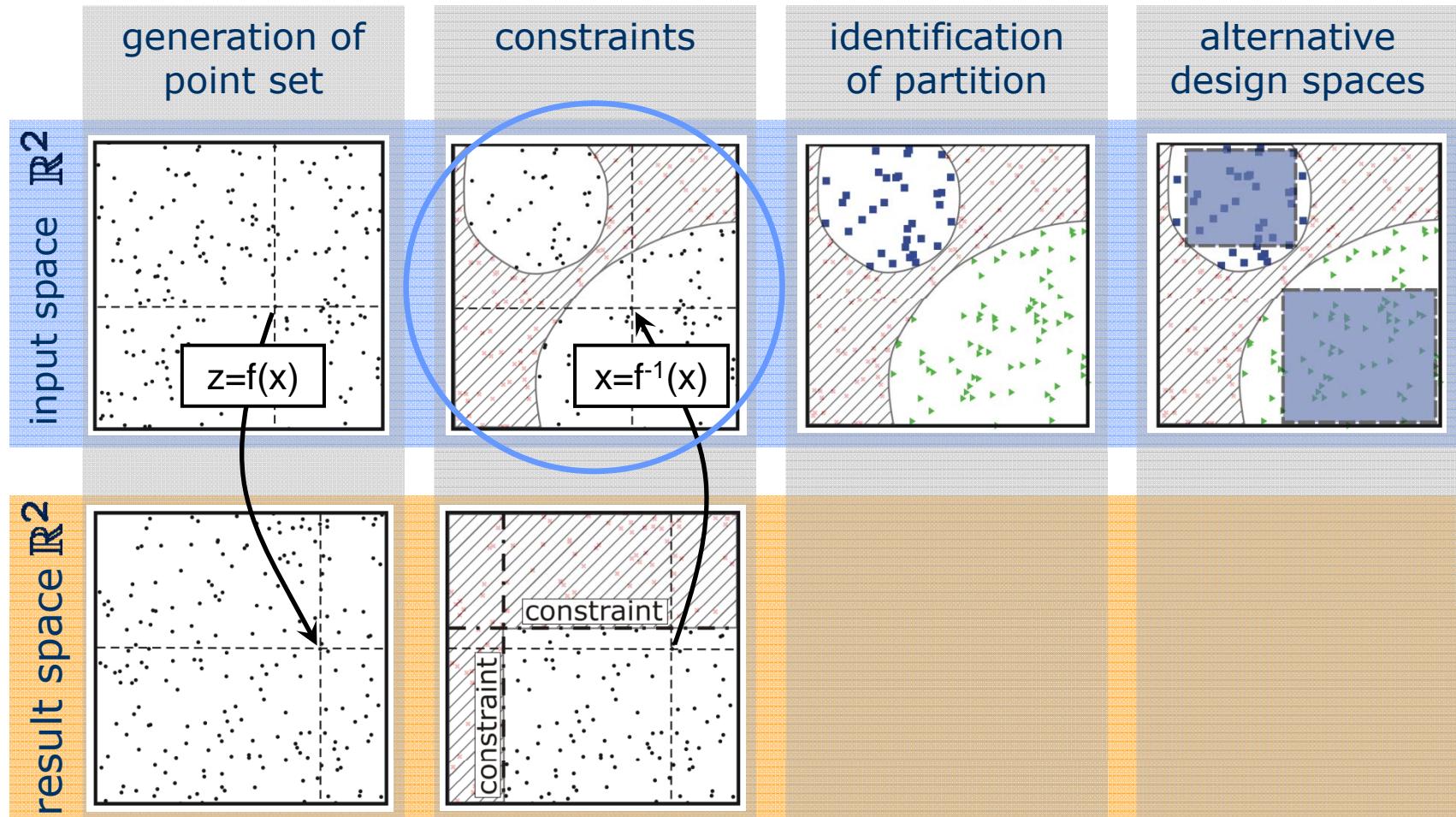
$$z_{\alpha,r} = \max_{x \in A_\alpha} f(x)$$

Fuzzy structural analysis



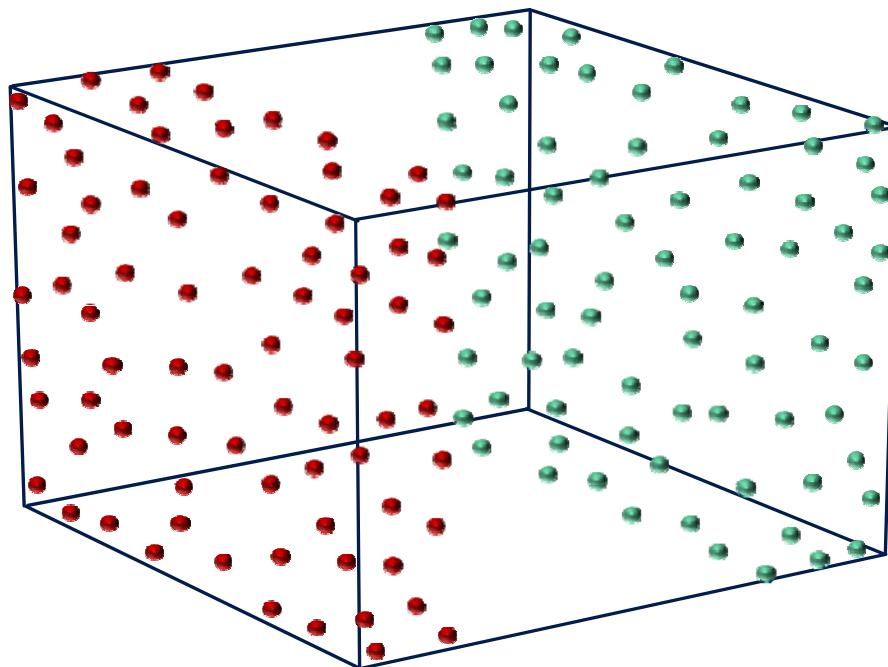
Specification of alternative design spaces

General scheme

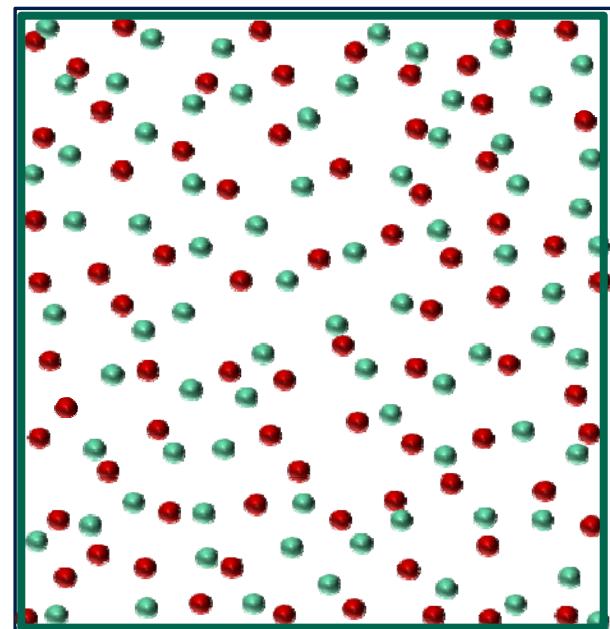


Dimensionality problem

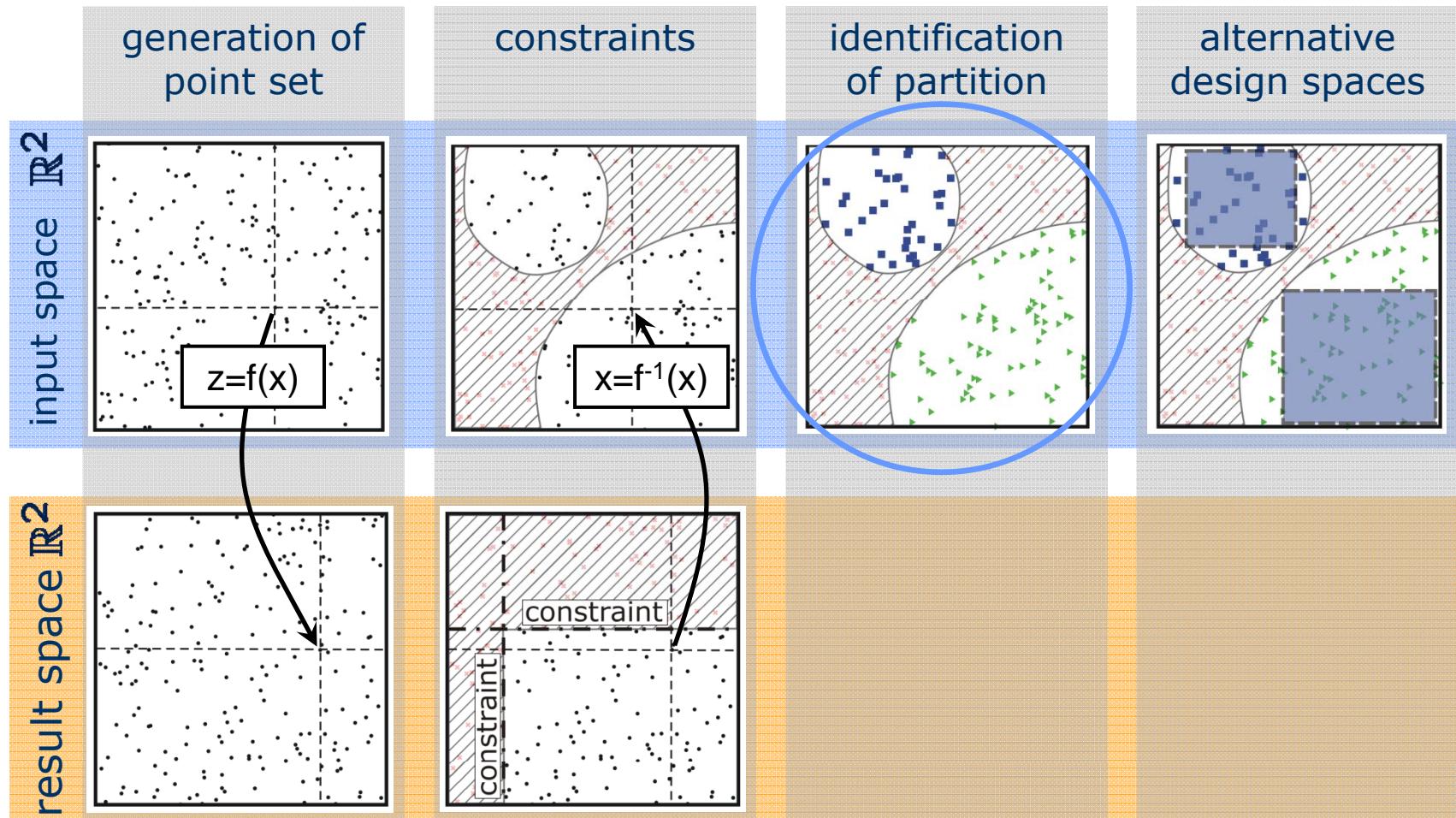
- more than sensitive 3 input quantities
- 3D



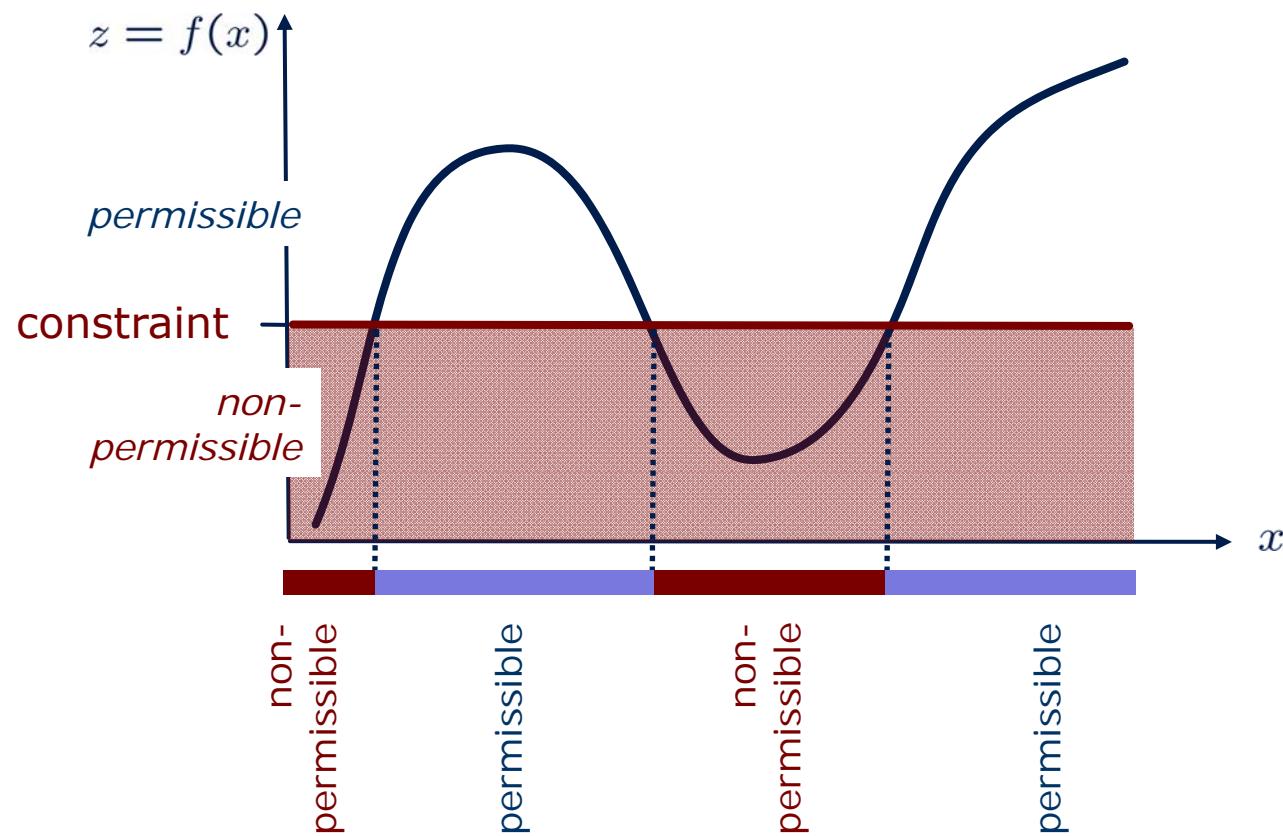
- 2D



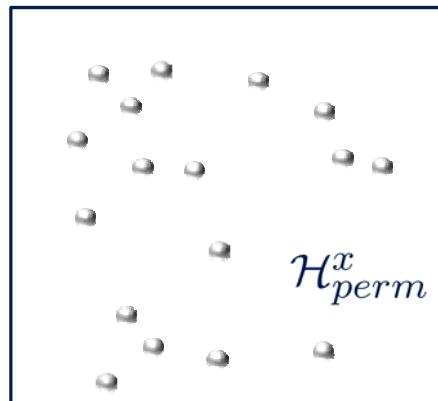
General scheme



Partition

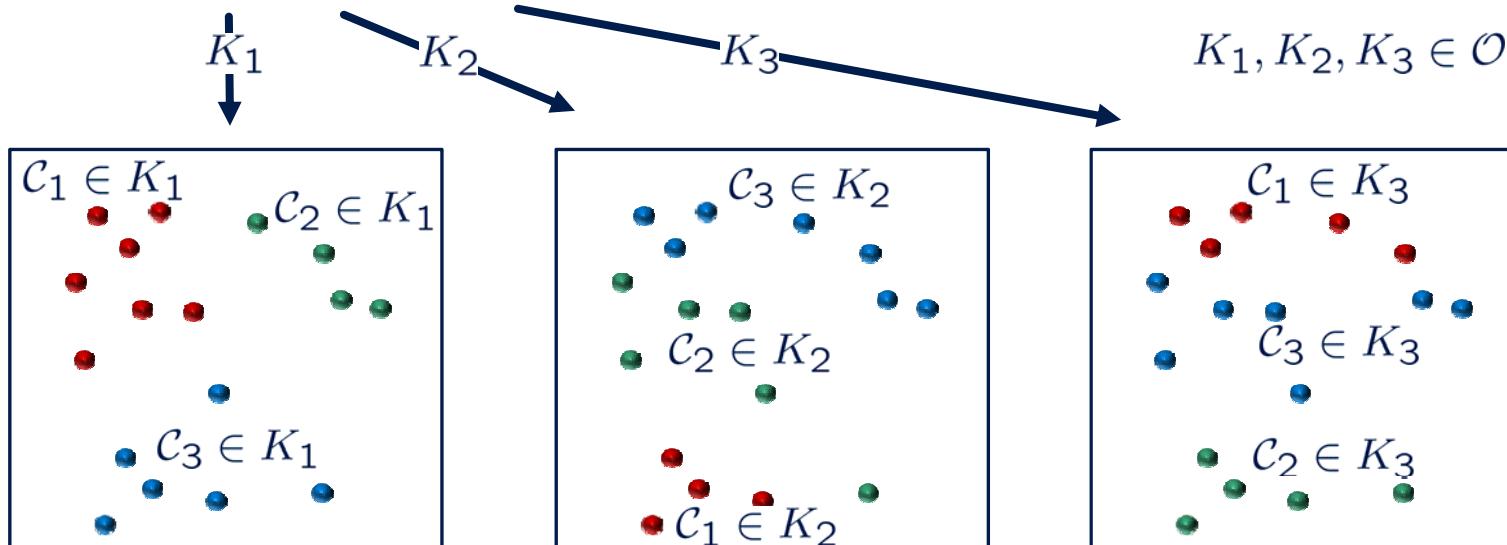


Cluster analysis – objective

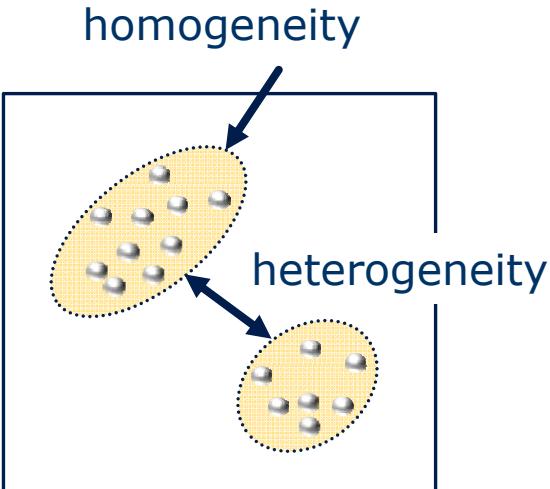


preconditions on clusters

- pairwise disjoint $\mathcal{C}_i \cap \mathcal{C}_j = \emptyset, \quad \mathcal{C}_i \neq \mathcal{C}_j$
- nonempty $\mathcal{C}_i \neq \emptyset$
- reproduce point set $\bigcup_i^{n_c} \mathcal{C}_i = \mathcal{H}_x^{\text{perm}}$



Cluster analysis – objective



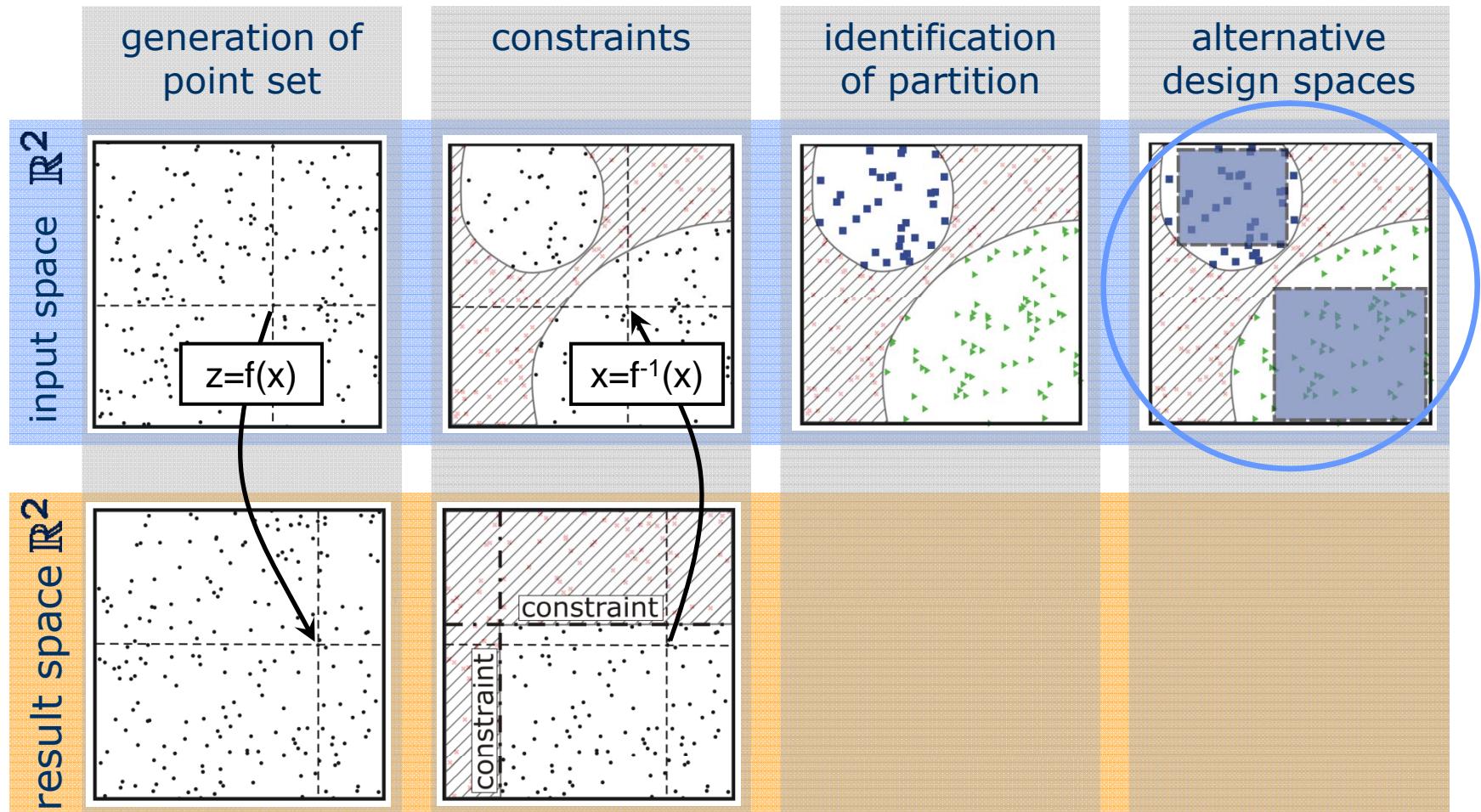
- **homogeneity**
points in a same cluster should be as similar as possible
 $\sum_{p,q \in \mathcal{C}_i} d(p, q) \rightarrow \min$
- **heterogeneity**
points of different clusters should be as dissimilar as possible
 $\sum_{p \in \mathcal{C}_i, q \in \mathcal{C}_j, i \neq j} d(p, q) \rightarrow \max$

determination of an appropriate cluster configuration K ;
optimization task $D(K) \rightarrow \min$

$$D : \mathcal{O} \rightarrow \mathbb{R} : K \mapsto \sum_{\mathcal{C}_i \in K} \sum_{p \in \mathcal{C}_i} d(p, \nu_i)^2$$

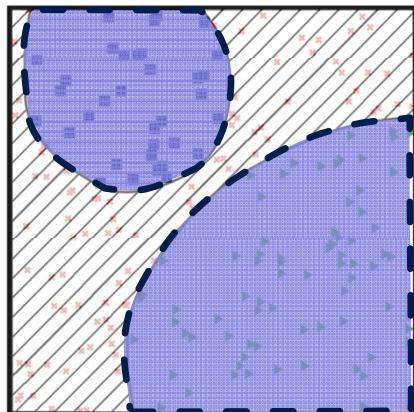
→ predefined number of clusters - challenge

General scheme

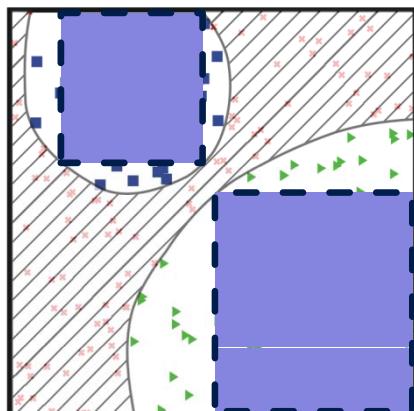


Alternative design space(s)

convex hull **vs.**
hypercuboid

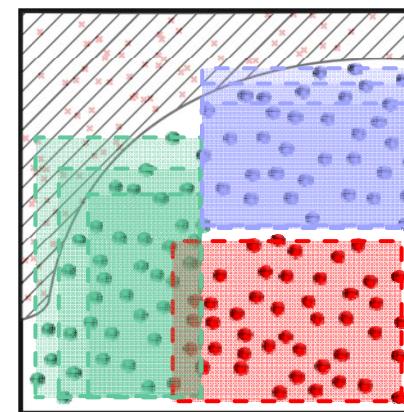


interacted design
variables
↓
ambitious
and expensive

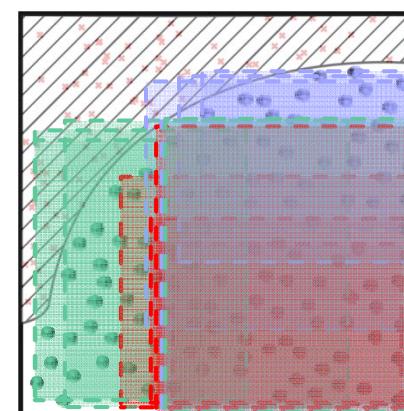


interaction-free
design variables

hypercuboids per cluster **vs.**
maximal possible hypercuboids



hypercuboid
bases on
available
point set



detection
of number of
non-connected
input spaces

Examples

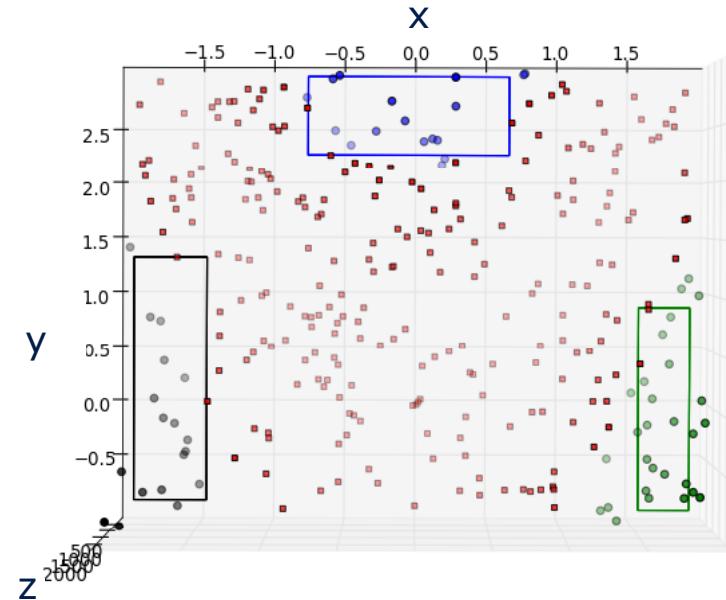
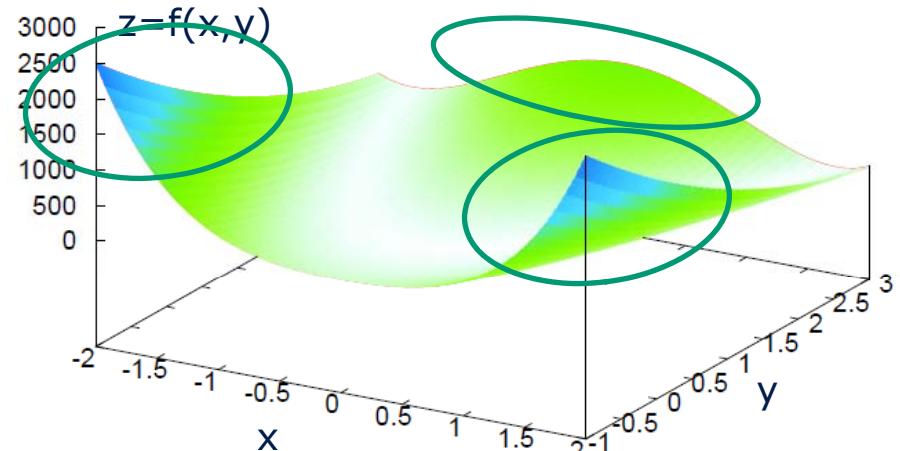
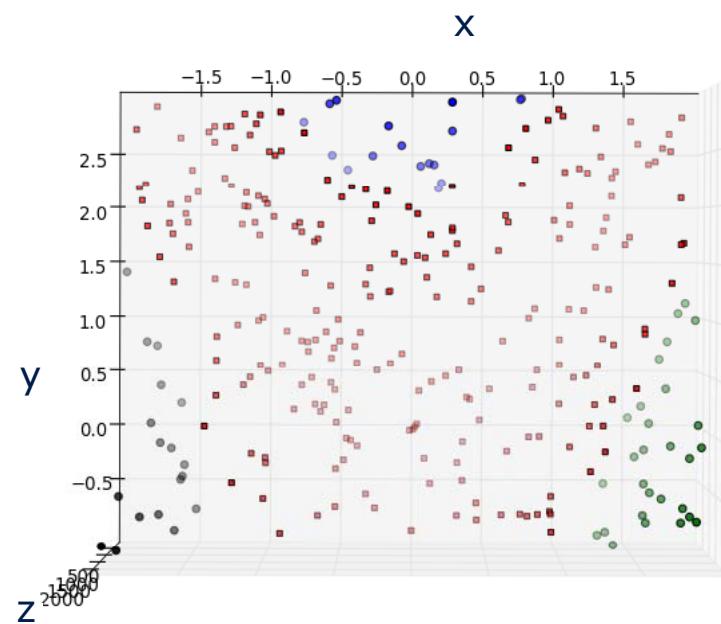
Rosenbrock function

$$z = f(x, y) = (1 - x)^2 + 100 (y - x^2)^2$$

$$x \in [-2; 2] \quad y \in [-1; 3]$$

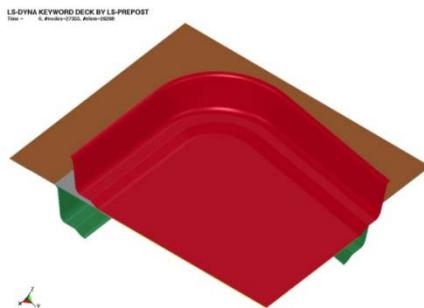
permissibility condition

$$z \geq 400$$

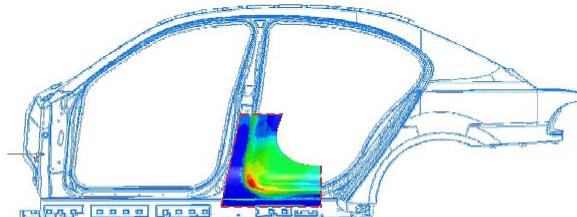


Model

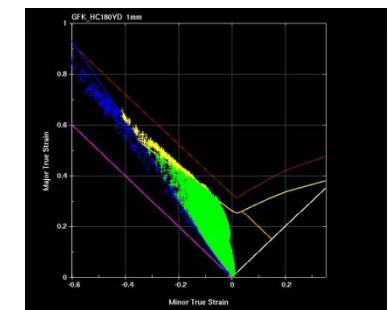
computational model



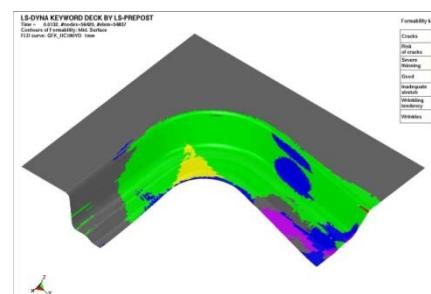
crack sensitive area



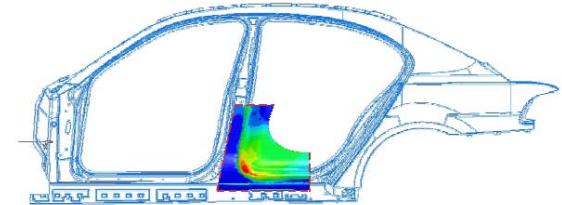
FLD



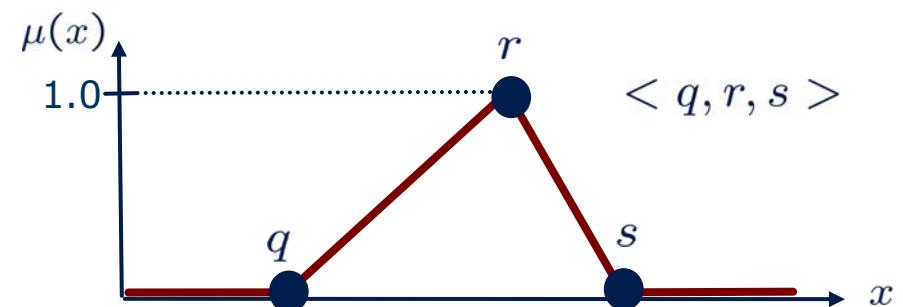
results



Reliability assessment – Fuzzy Analysis



Input parameters		Delivery tolerances	Fuzzy quantities
yield stress	Rp02	180 ... 230	<180, 205, 230>
tensile strength	Rm	340 ... 420	<340, 380, 420>
hardening exponent	n	0.20 ... 0.30	<0.20, 0.22, 0.30>
anisotropy	R90	1.80 ... 4.00	<1.80, 2.40, 4.00>



Reliability assessment – fuzzy analysis

- evaluated results

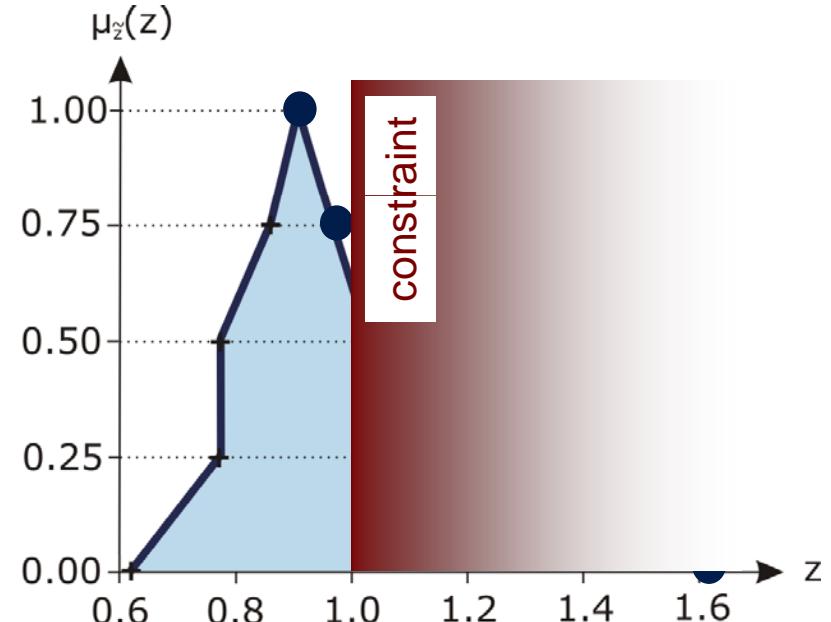
(Grossenbacher 2008)

$$\left. \begin{array}{l} \text{cracking } z_c = f_1(x) \\ \text{thinning } z_t = f_2(x) \end{array} \right\} z := \max(z_c, z_t) \quad z_{lim} = 1.0$$

- fuzzy result quantity \tilde{z}

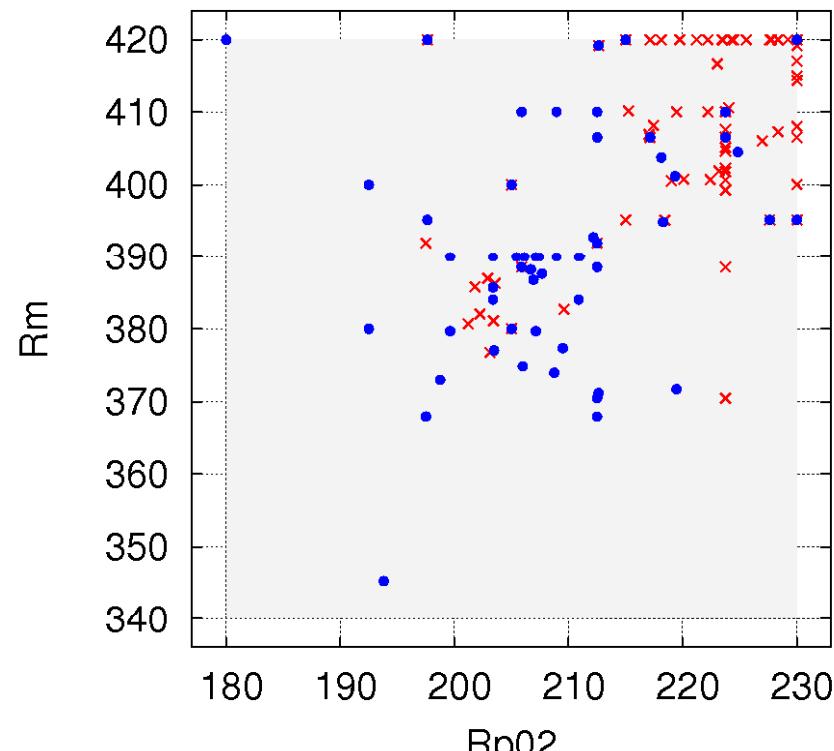
- number of α -levels: 5
- determined interval bounds of α -level:
 $z_{\alpha=0,r}, z_{\alpha=0.25,r}, z_{\alpha=0.5,r}$
 $z_{\alpha=0.75,r}, z_{\alpha=0.25,r}$

- simulations runs: 150



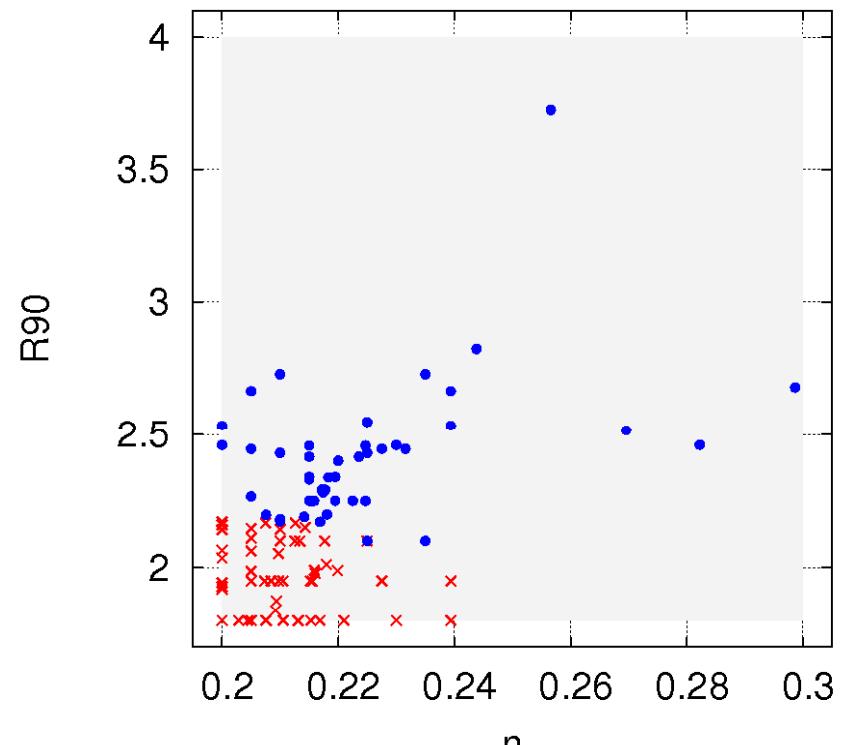
Constraints

cross-plot: R_{p02} – R_m



● *permissible*

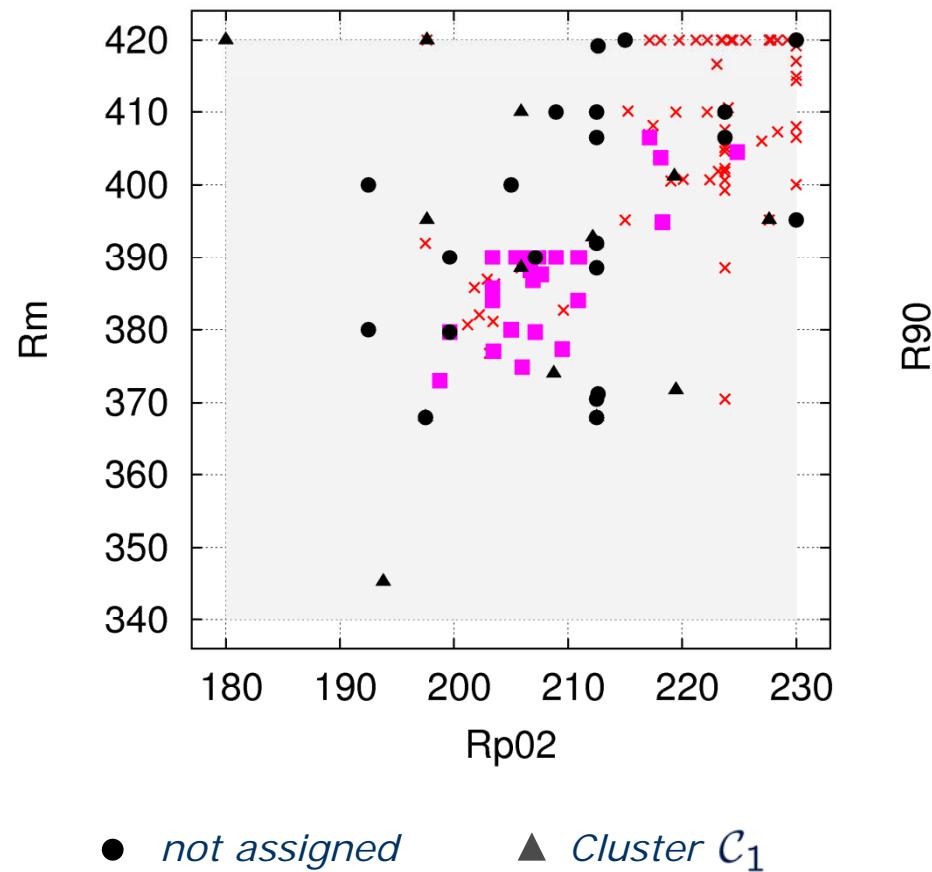
cross-plot: n – R_{90}



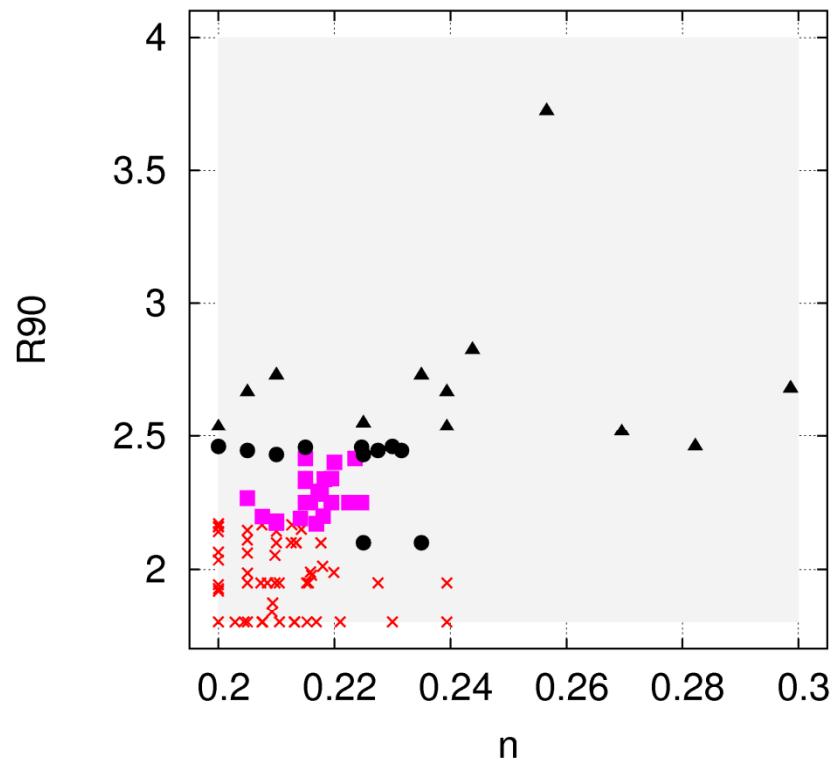
✗ *non-permissible*

Partitioning – cluster analysis

cross-plot: R_{p02} – R_m



cross-plot: n – R_{90}



\bullet *not assigned*

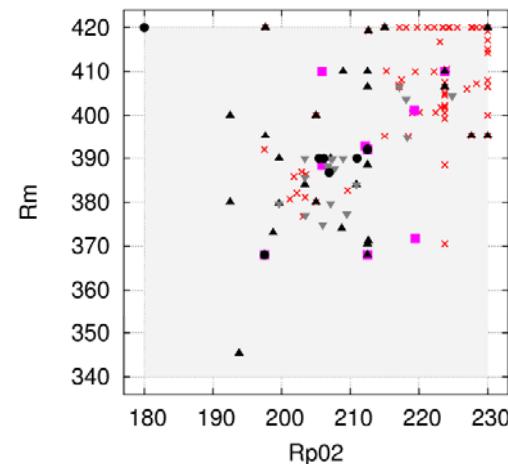
\blacktriangle *Cluster C_1*

\blacksquare *Cluster C_2*

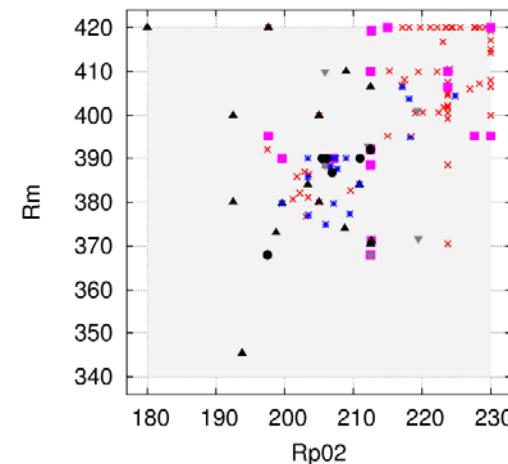
\times *non-permissible*

Partitioning – cluster analysis

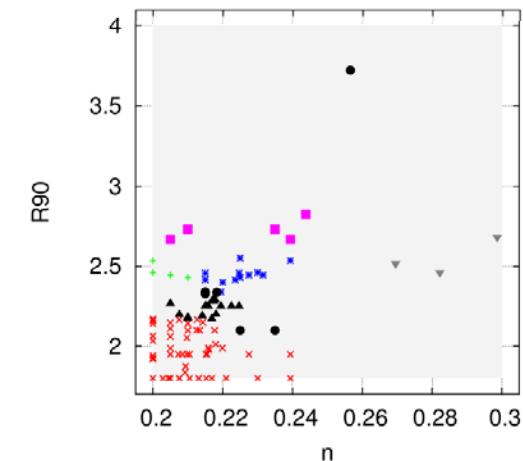
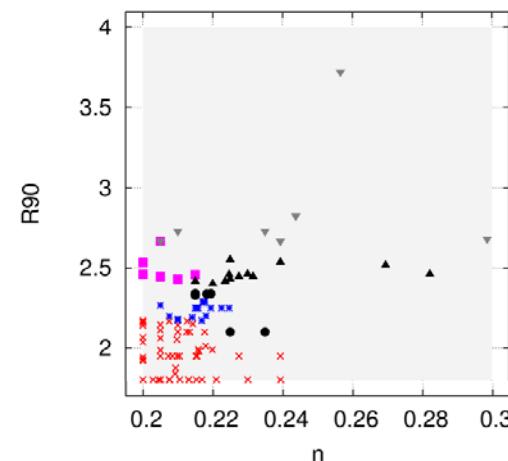
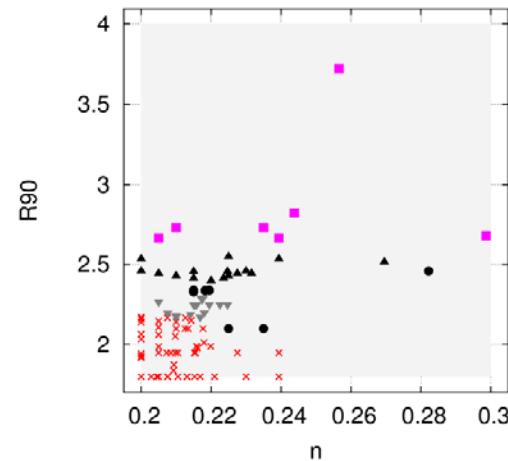
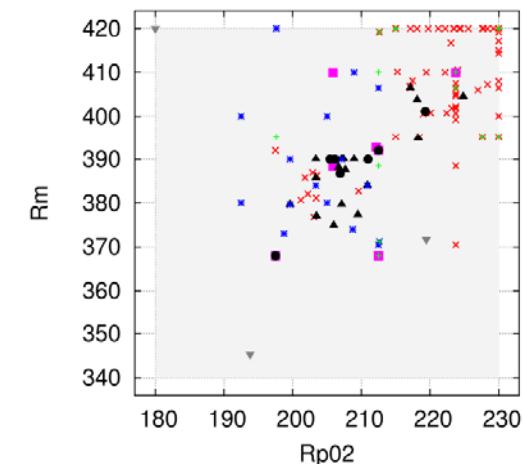
3 cluster



4 cluster

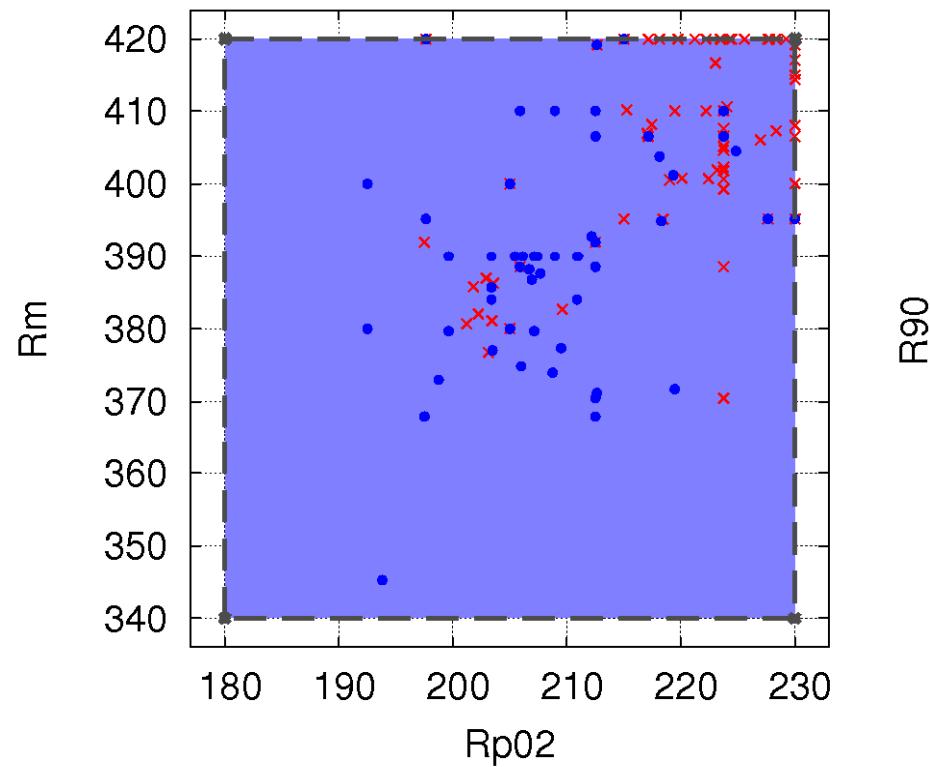


5 cluster

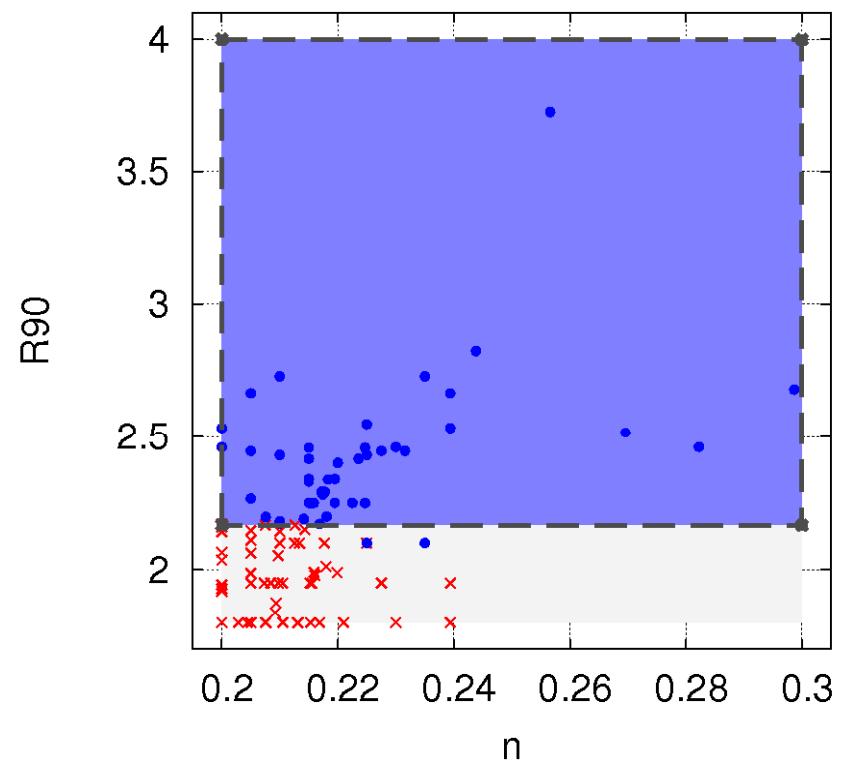


Alternative design space

cross-plot: R_{p02} – R_m



cross-plot: n – R_{90}

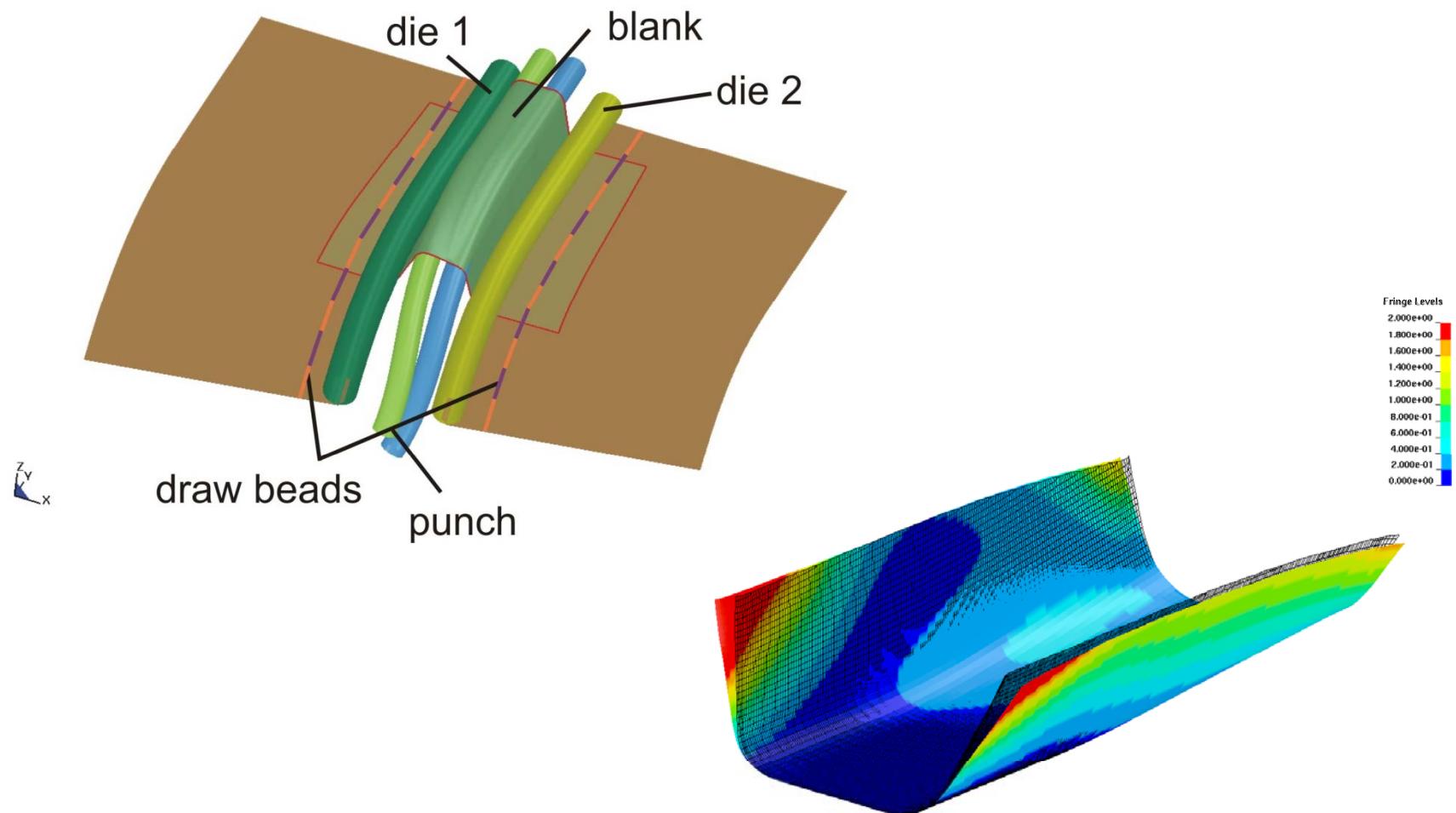


alternative design space

● permissible

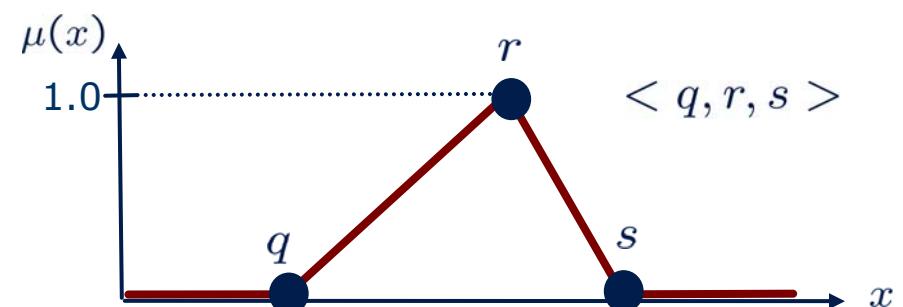
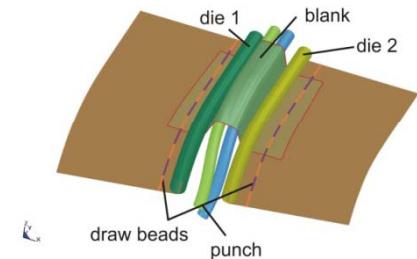
✖ non-permissible

Model



Input quantities

input parameter	ranges	fuzzy quantities
radius die 1	8 ... 12	$< 8, 10, 12 >$
radius die 2	8 ... 12	$< 8, 10, 12 >$
draw bead force 1	0 ... 300	$< 0, 200, 300 >$
:	:	:
draw bead force 22	0 ... 300	$< 0, 200, 300 >$
shell thickness	0.45 ... 0.5	$< 0.45, 0.475, 0.5 >$
binder force	100 ... 300	$< 100, 200, 300 >$
positioning blank		
x-direction	-2 ... 2	$< -2, 0, 2 >$
positioning blank		
y-direction	-2 ... 2	$< -2, 0, 2 >$



Reliability assessment – fuzzy analysis

- evaluated results

$f_1(x)$ – geometry

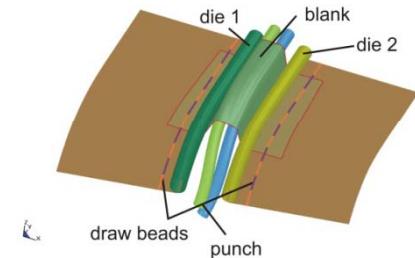
$$f_1(x) \leq 30,000$$

$f_2(x)$ – cracking (FLC)

$$f_2(x) \leq 1.0$$

$f_3(x)$ – manufacturing

$$f_3(x) \leq 30.5$$



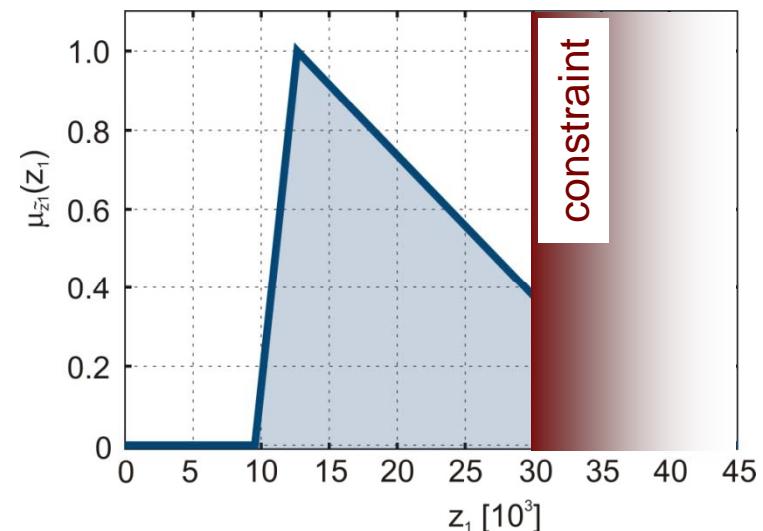
- fuzzy result quantity \tilde{z}_1

➤ number of α -levels: 2

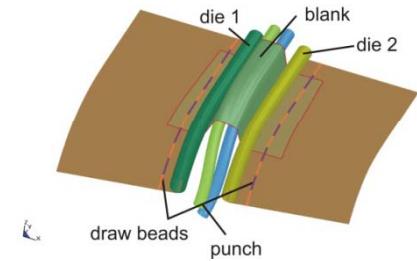
➤ determined interval bounds of α -level:

$$z_{\alpha=0,r}, z_{\alpha=1.0,r}$$

➤ simulations runs: 232



Demonstrator



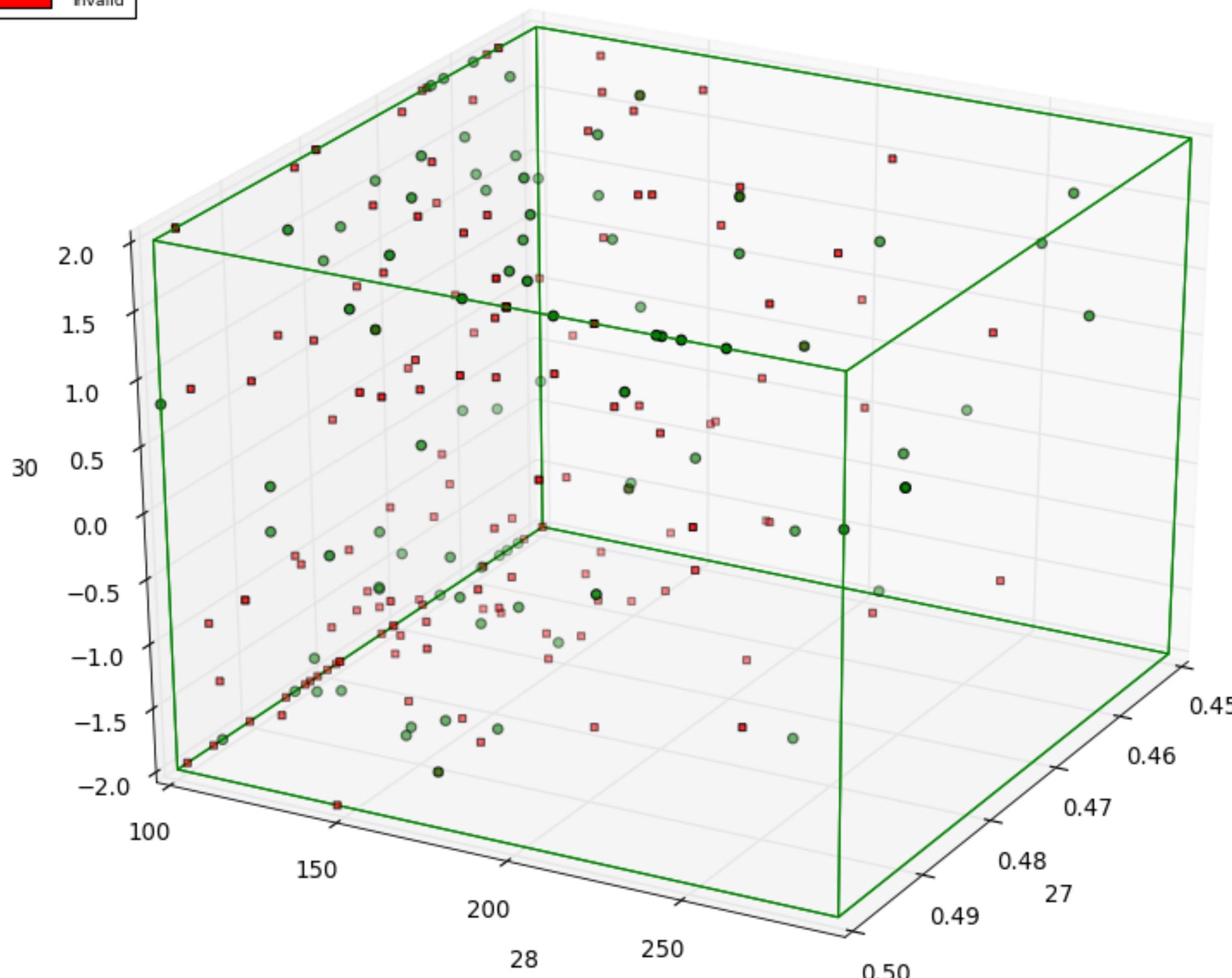
Determination of
alternative design spaces

File Ansicht

Data 2 Design Space 2

Graph

- Box 1
- Invalid



Limits

Design Box

Box 1 Limits

	Min	Max
1	10.0	10.0
2	10.0	10.0
3	8.0	11.87426949
4	8.0	12.0
5	0.0	282.34641423
6	0.0	300.0
7	4.48244455	290.0
8	9.00050319	300.0
9	18.63258605	300.0
10	39.20208906	300.0
11	0.0	300.0
12	4.2021211	300.0
13	23.73806075	300.0
14	0.0	300.0
15	0.0	300.0
16	0.0	300.0
17	0.0	300.0
18	0.0	300.0
19	0.0	289.01857997
20	1.86708808	288.54278662
21	0.0	300.0
22	12.62466908	300.0
23	15.68803686	282.87587561
24	1.87204647	300.0
25	-1.40041872	300.0
26	1.54838355	300.0
27	0.44999999	0.5
28	100.0	291.99404907
29	-2.0	2.0
30	-2.0	2.0

Controls

X-Axis 27 Y-Axis 28 Z-Axis 30 Valid Points 87 Invalid Points 145

 Show Invalid Points Show Boxes

Number of Boxes 1 1 4

Conclusions

- assessment of reliability in an early design stages reasonable
- determination of alternative design spaces instead of an optimal design
- detection of non-connected point sets with cluster analysis
- assignment of hypercuboids to clusters – only permissible points
- applicability is underlined by means of an industry-relevant example

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