

CRASHWORTHINESS and Test Strategies for High Strain Rate Testing

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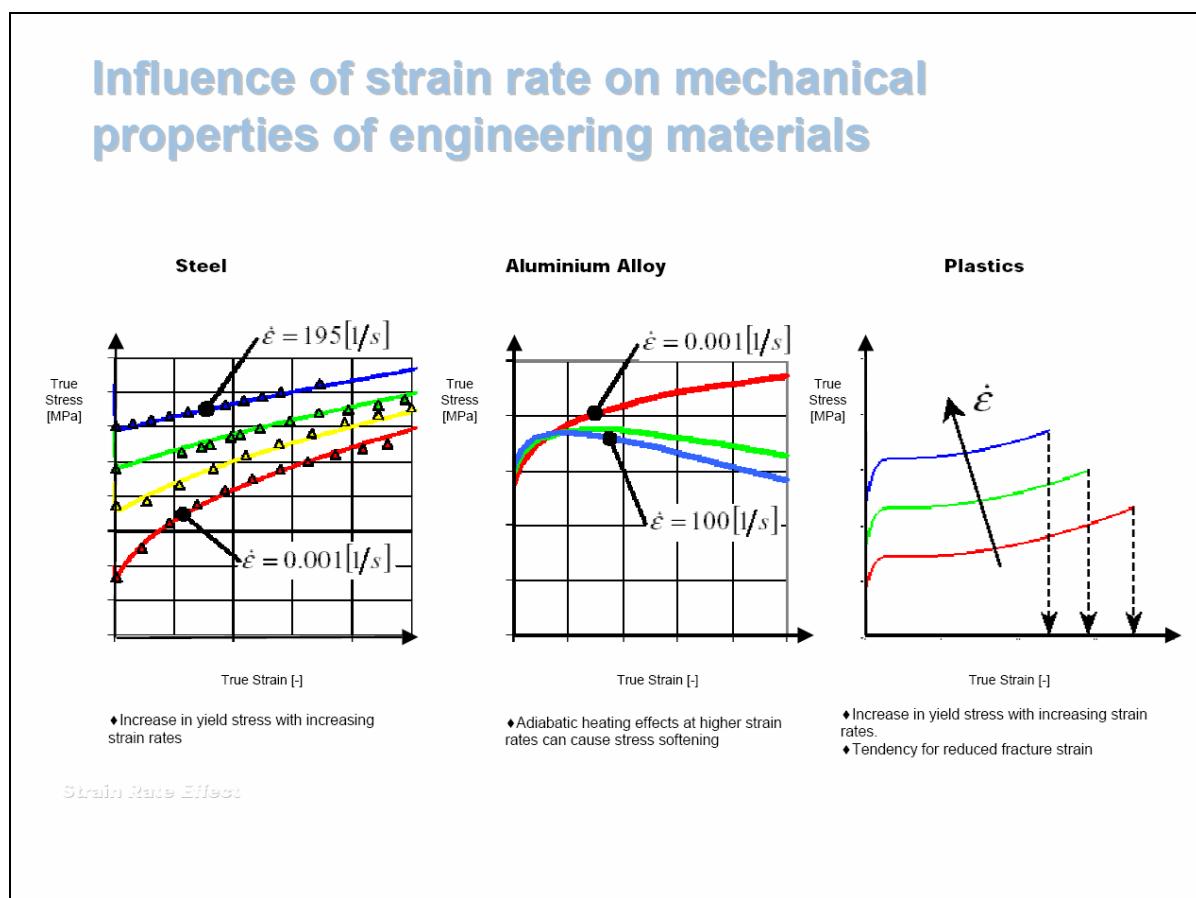
Instron Deutschland GmbH



Dr.-Ing. Reinhard Bardenheier
Graham P. Rogers

CRASHWORTHINESS and Test Strategies for High Strain Rate Testing

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Material models

Descriptive

Johnson-Cook Model

$$\sigma = (A + B \epsilon^n) [1 + C \ln(\frac{\epsilon}{\epsilon_0})] (1 - T^{*m})$$

A, B, C, m, n : Material constants

$$T^* = \frac{T - T_{room}}{T_{melt} - T_{room}} \quad \epsilon_0 = 1/\text{sec}$$

Cowper-Symonds Model

$$\sigma = \sigma_0 (\epsilon) [1 + (\frac{\epsilon}{D})^{\frac{1}{p}}]$$

σ_0 : Static stress

D, p : Material constants

$$\sigma_0 (\epsilon) = k (\epsilon_{yp} + \bar{\epsilon})^n$$

Simulation



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Typical Framework for the Materials Verification Process



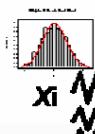
Validate material input data to FEA



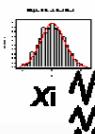
Validate material data in components & sub-assemblies



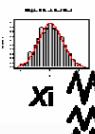
Validate material data in full vehicle assembly



FEA model of sub-system



FEA model of sub-system



FEA model of system

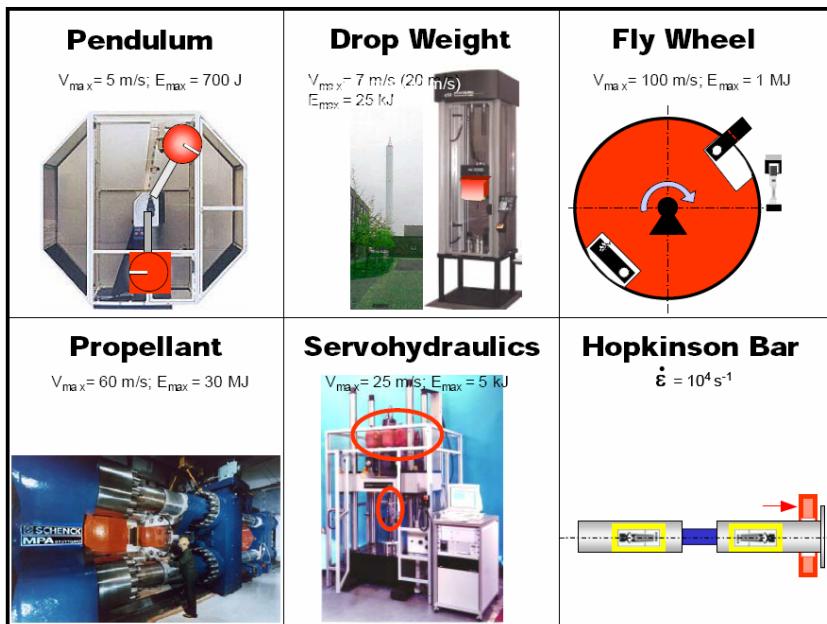
Simulation

[Wood, Warwick Uni, 2005]



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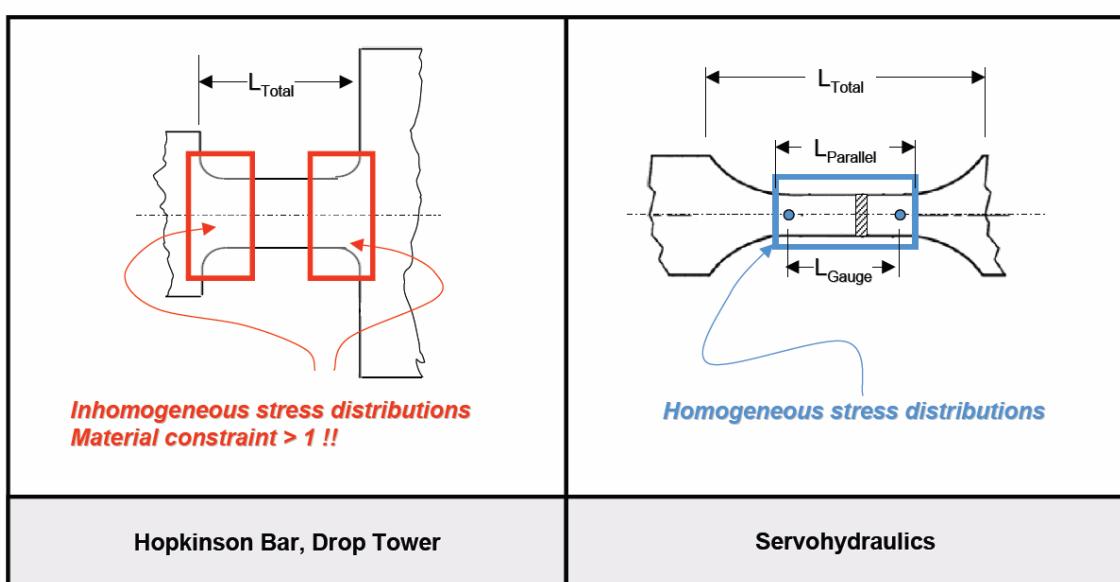
Impact Test Facilities



High Strain Rate Test

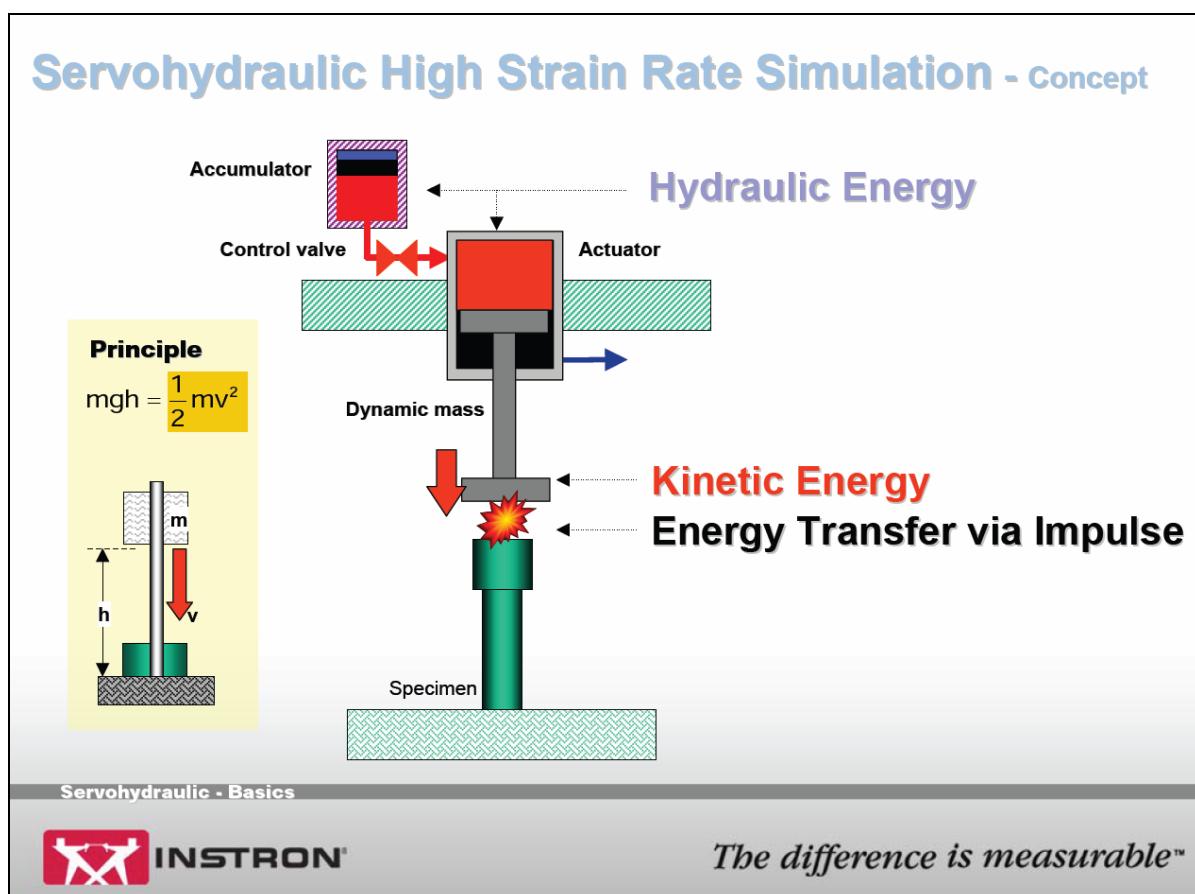
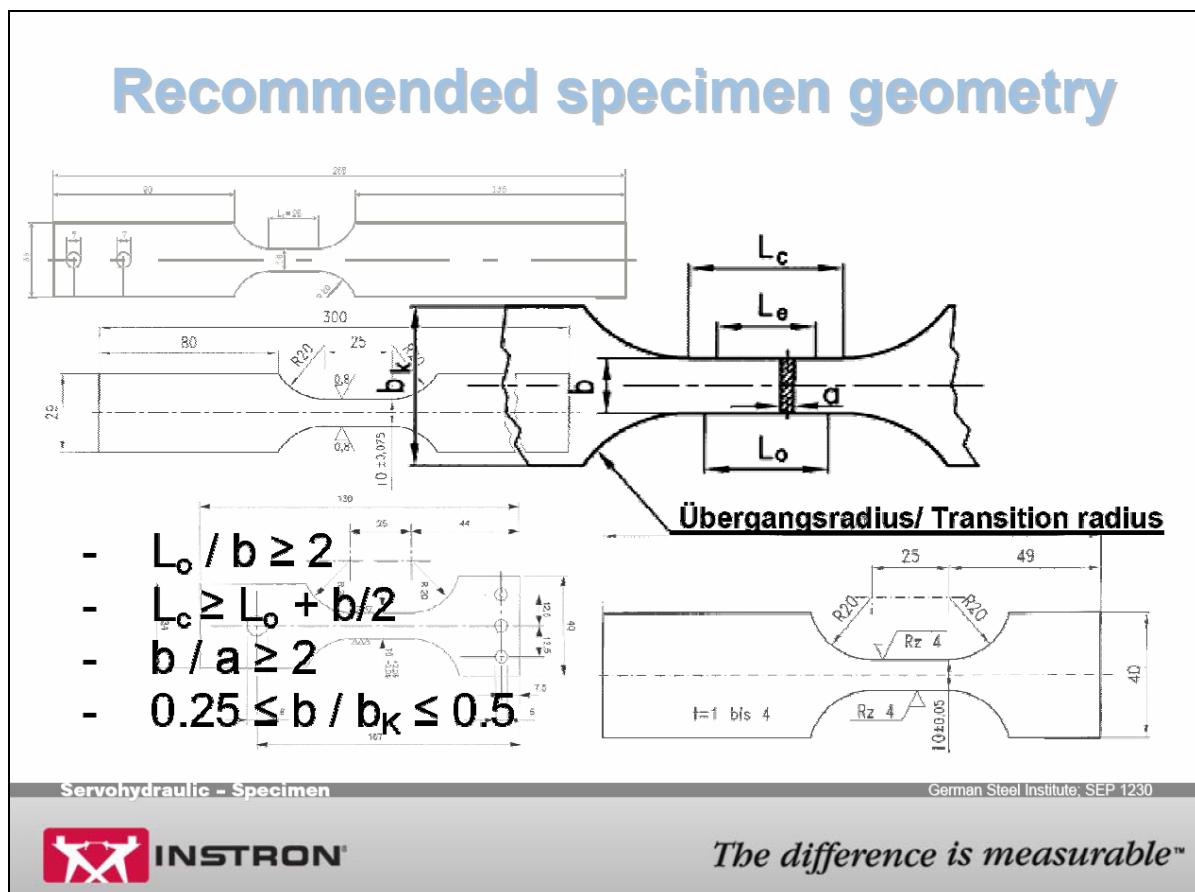
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Consequences of specimen geometries



Servohydraulic - Specimen

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Load Frames



VHS25/25-20
VHS40/50-20
VHS65/80-20/{25}

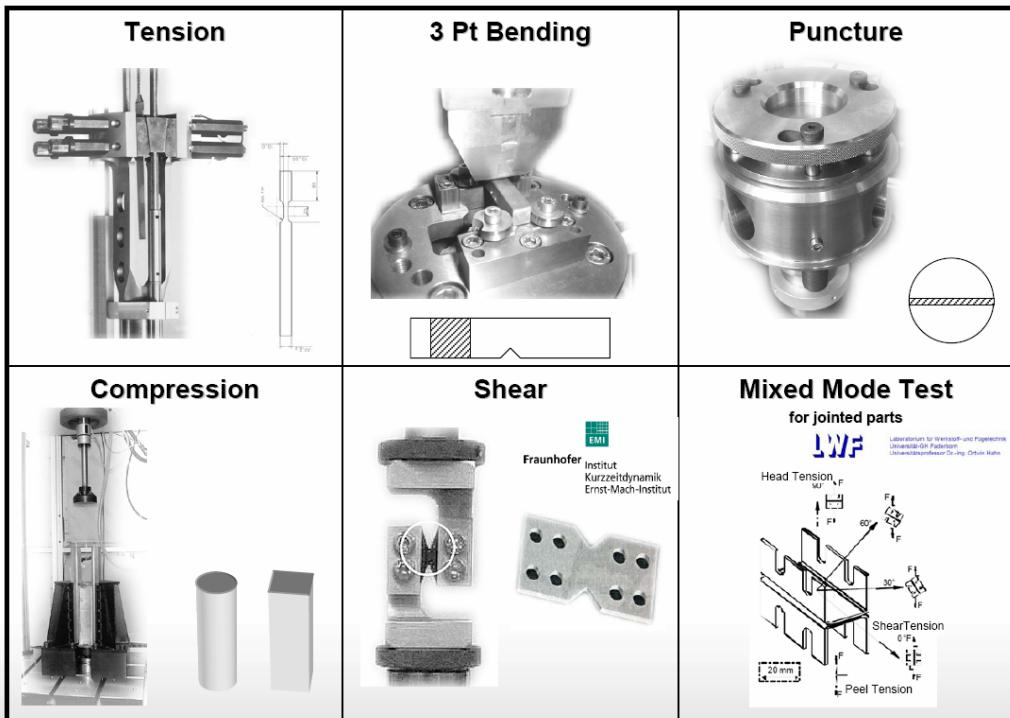


VHS65/80-20/{25}
VHS160/100-20

Servohydraulic - Loading Unit



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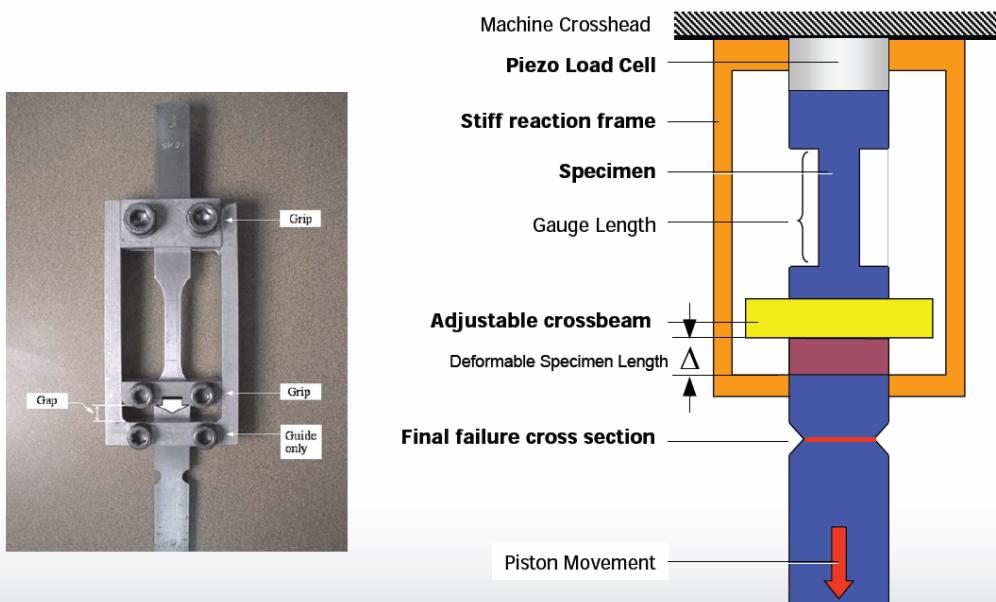
Servohydraulic - Test Accessories



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Possible Test Set-up for a blocked High Strain Rate Tension Tests

Influence of impact preloading on mechanical behaviour – residual strength



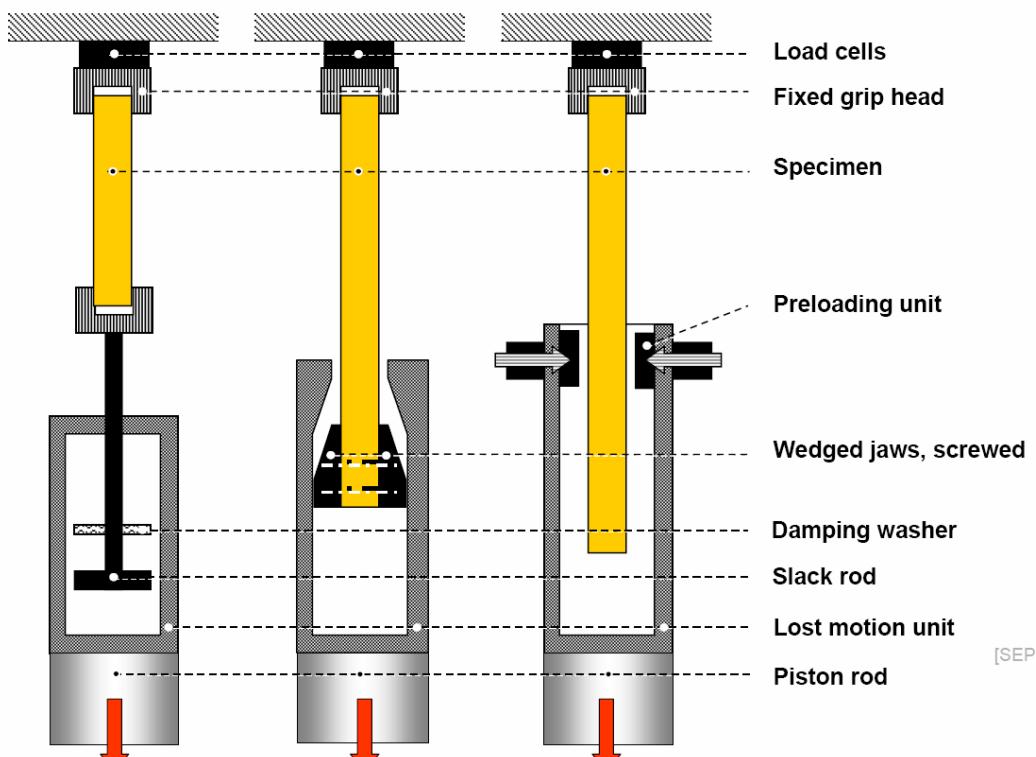
Servohydraulic - Special Tests

[Chai et al., 2002]

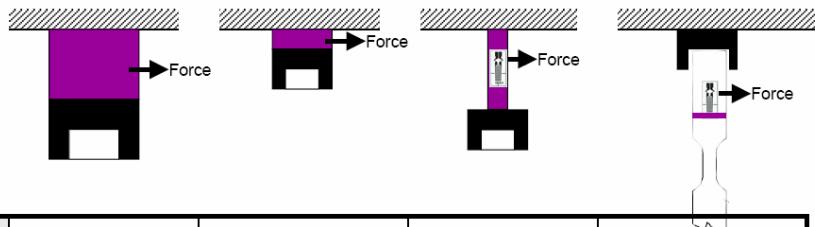


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Acceleration and Clamping Methods



Load Measurement Method

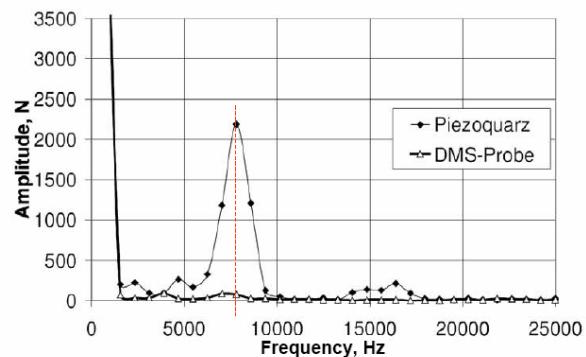
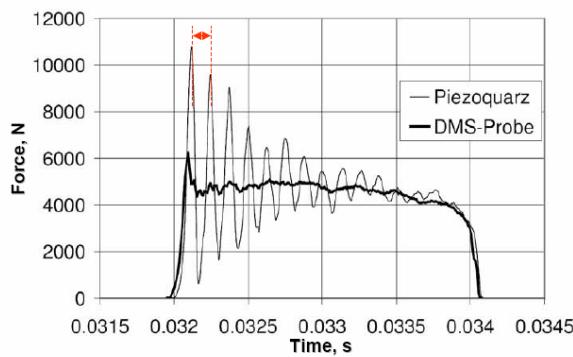


| Load Measurement Method | Conventional load cell | Piezo-electric load washer | Special compact load measurement element | Instrumented specimen |
|--------------------------------------|--|---|--|---|
| Upper strain rate limit [s^{-1}] | 10^1 | 10^2 | 5×10^2 | 10^3 |
| Lower strain rate limit [s^{-1}] | None | 10^0 | None | None |
| Note: | Oscillation of measured load may be large at low strain rate already | Beyond the upper limit major oscillations may be superposed on the mechanical load signal | | Strain gauge should be attached at a place that is free from plastic deformation during loading |

Servohydraulic - Force

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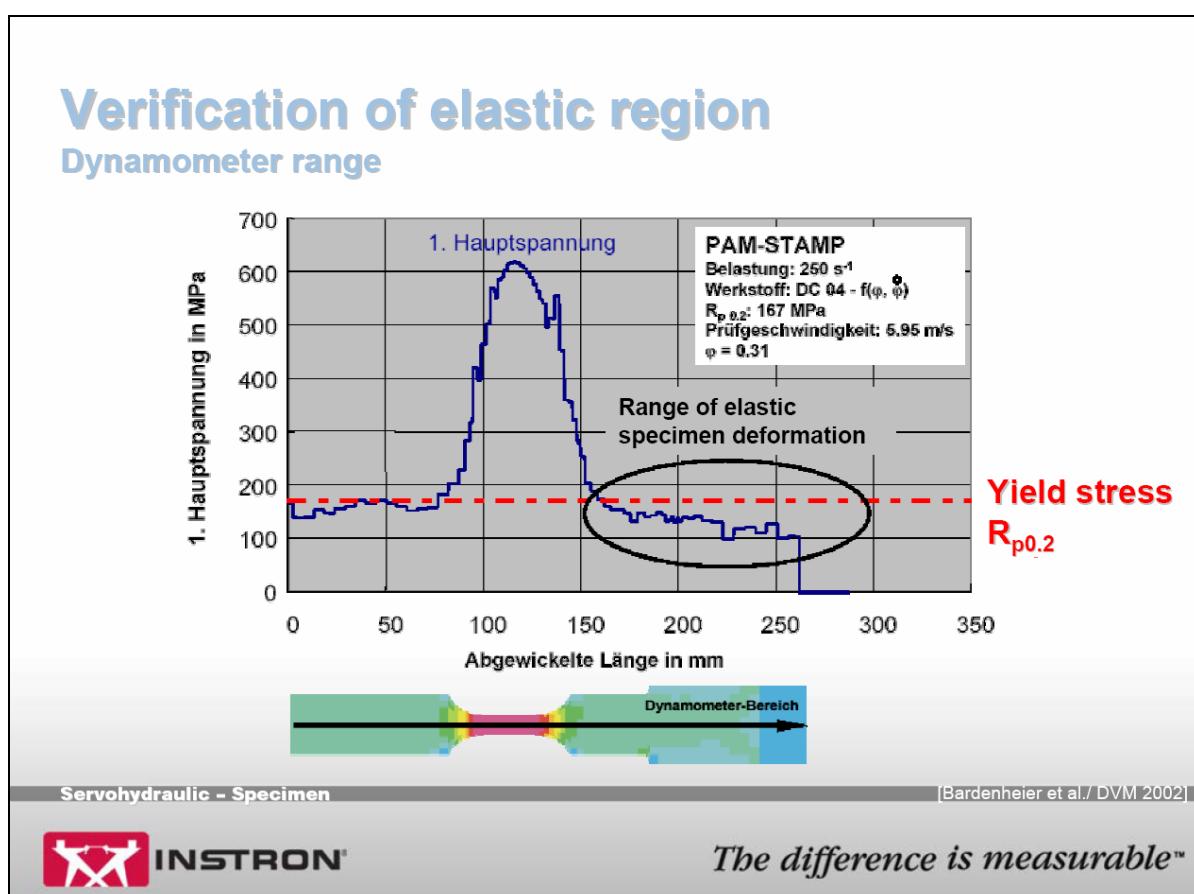
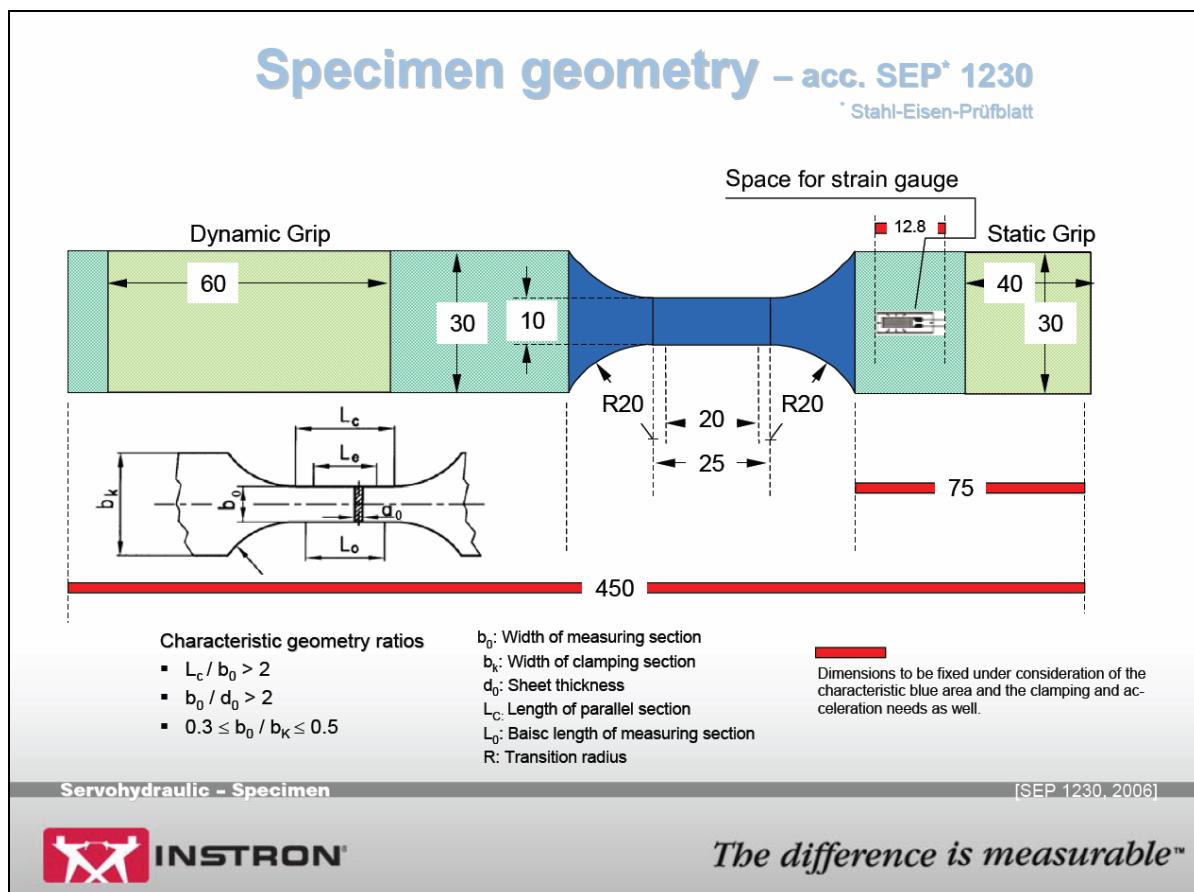
FFT-Analysis of Load Signal

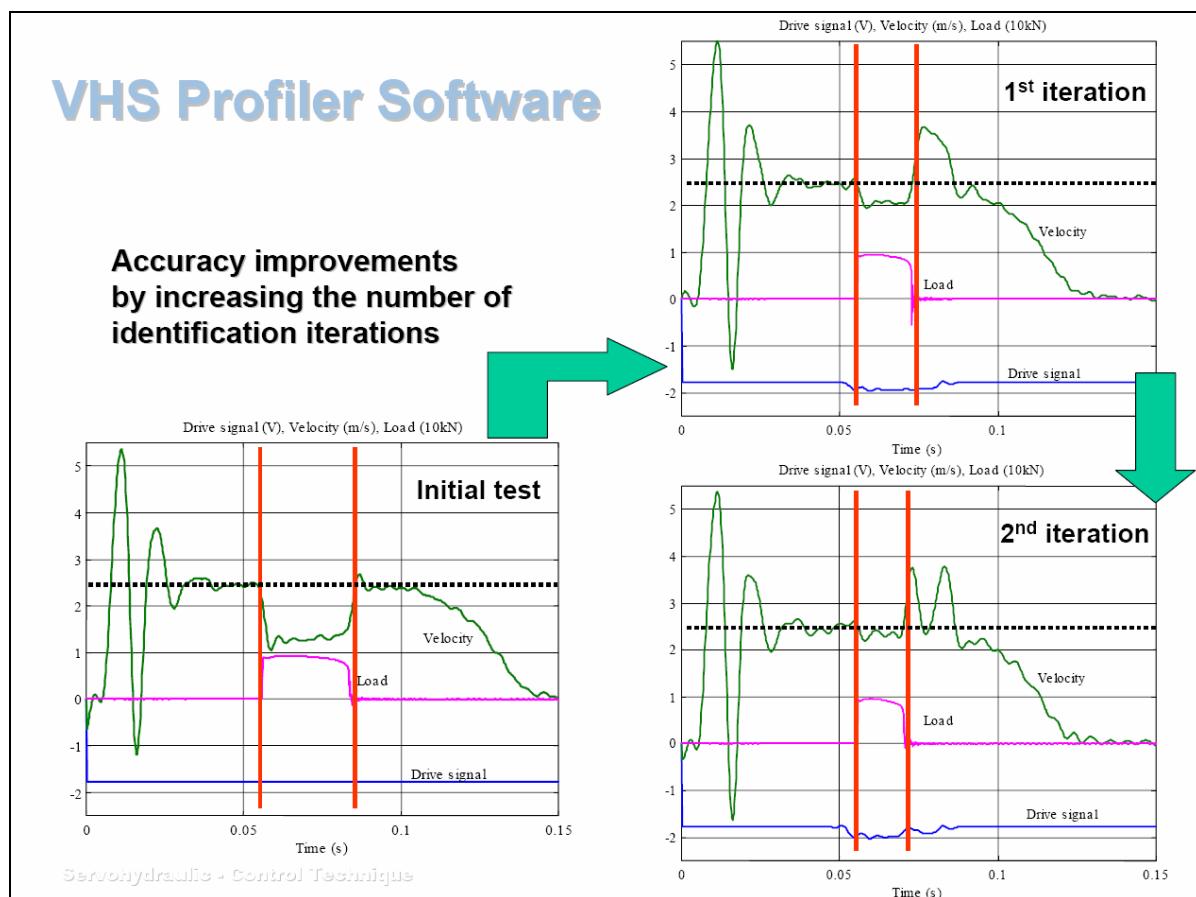
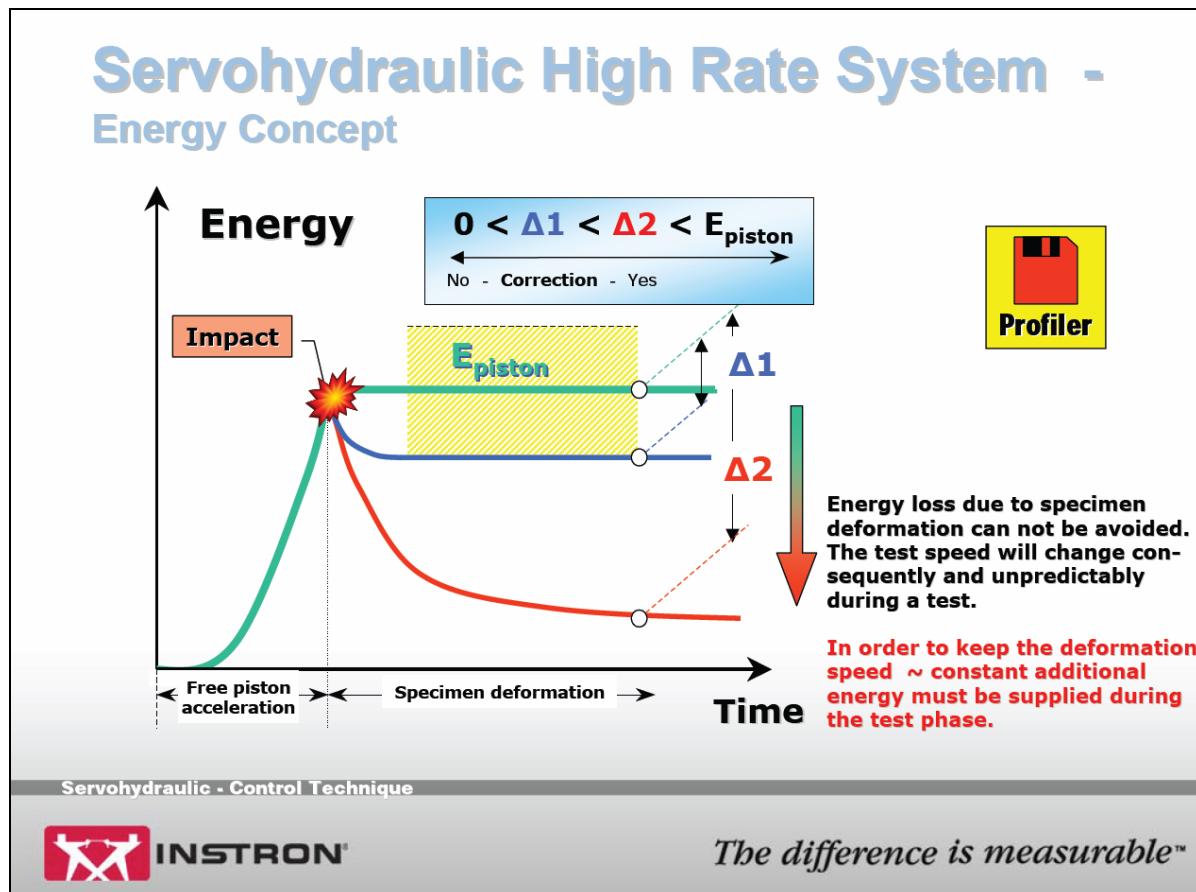


Wolfgang Bleck, Patrick Larour, Annette Bäumer, Julio Noack
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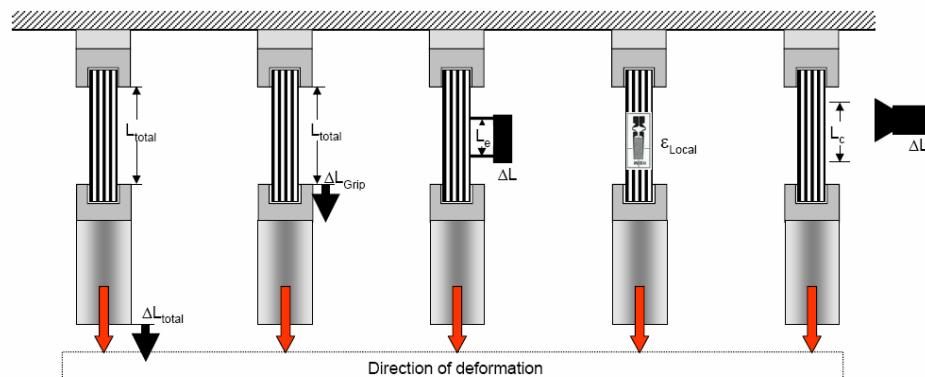
Servohydraulic - Force

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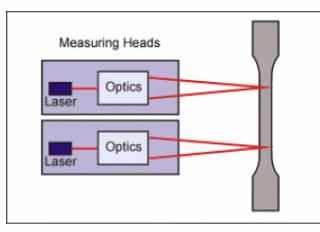
Displacement / Strain Measurements



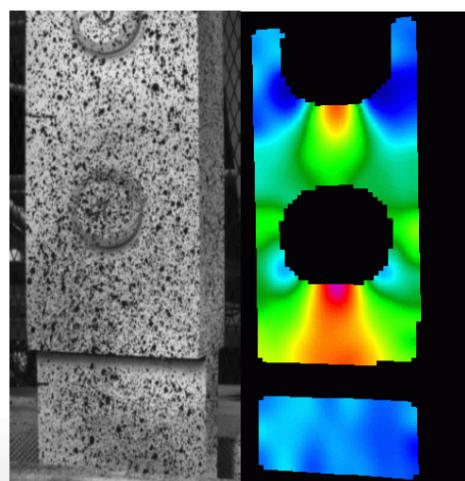
| Method | Actuator Piston or Crosshead Movement | Griphand Displacement | Conventional Extensometer | Strain Gauge | Non-contact Extensometer |
|--------------------------------------|--|---------------------------------------|--|---|---|
| Displacement / Strain Measurement | Conventional displacement transducer | Laser, Optical device | Clip-on Extensometer | Strain gauges for high strains | Laser-Doppler, High-Speed Camera |
| Upper strain rate limit [s^{-1}] | None | None | 10 ⁰ | None | None |
| Note: | Not recommended! Signal contains machine deformations as well. Poor resolution | Reference gauge length is L_{total} | Due to inertia effects limited to quasi-static deformations only | Strain measurements are limited by the max. strain measurable | Lower strain rate limit for Laser-Doppler is ~ 1 s^{-1} ; ref. to $L_0 = 25\text{mm}$ |

HR - Extensometry

Integral strain



Local strain

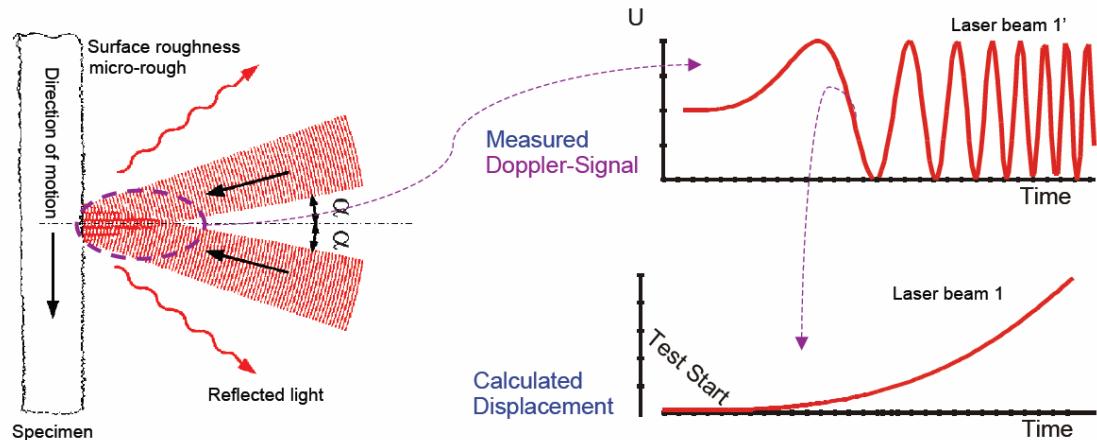


Servohydraulic - Strain Measurement



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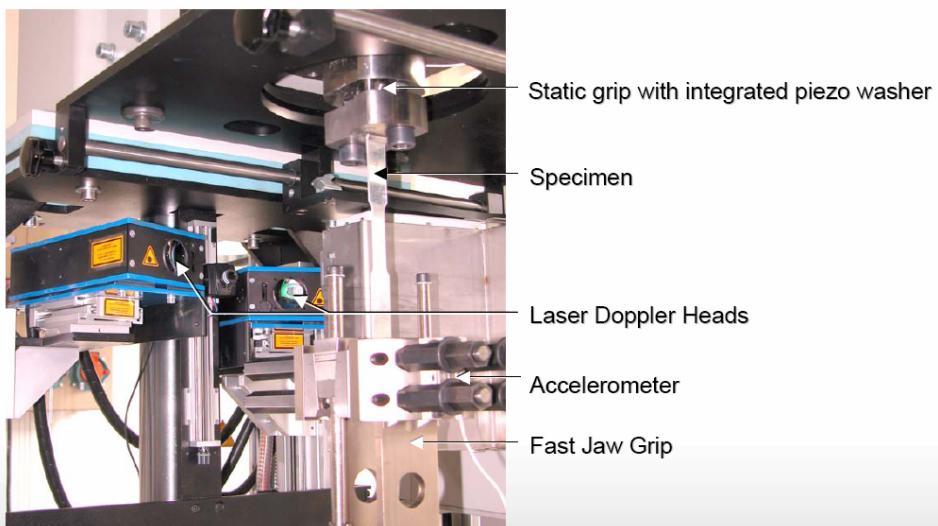
Interference fringe pattern on a moving surface



Servohydraulic - Strain Measurement

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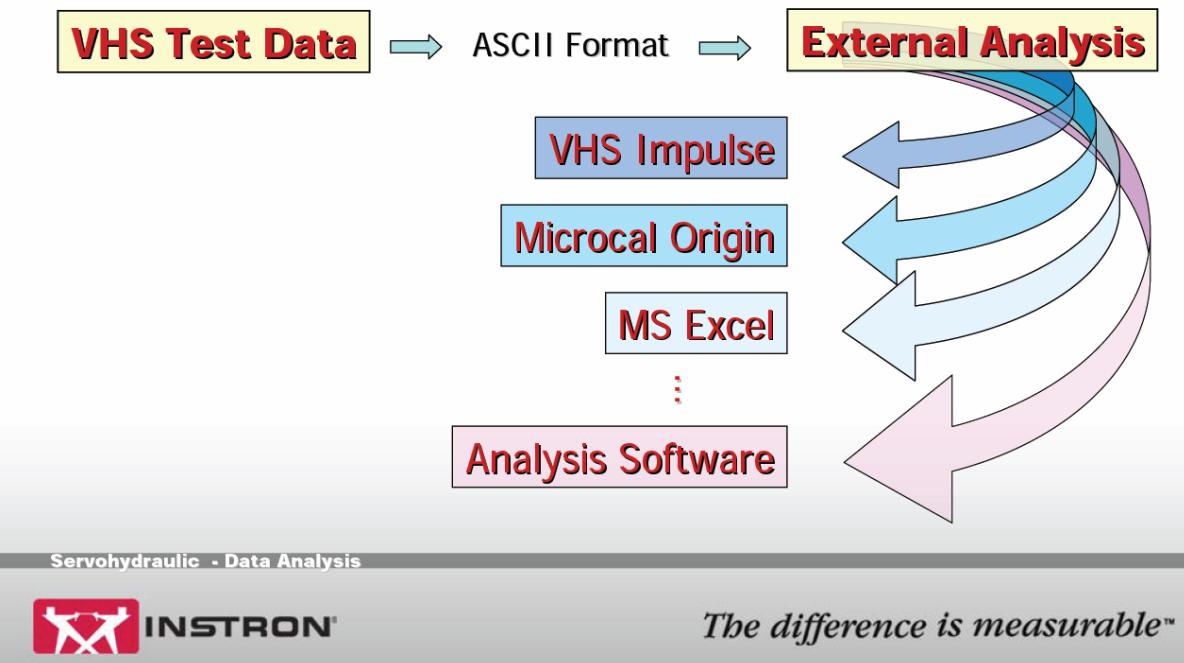
Test Setup with Laser Doppler Extensometer



Servohydraulic - Strain Measurement

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Export of Test Data



Strain Rate Definitions

■ Nominal strain rate

$$\dot{\epsilon}_{\text{nominal}} = \frac{V_{\text{impact}}}{L_0}$$

| | |
|----------------------------|------------------------|
| A | Strain to fracture |
| L_0 | Gauge length |
| t_f | Time to fracture |
| V_{impact} | Impact speed |
| $\dot{\epsilon}(t_{R_p1})$ | Strain rate @ R_{p1} |
| $\dot{\epsilon}(t_{R_m})$ | Strain rate @ R_m |

■ Mean technical strain rate

$$\dot{\epsilon}_{\text{mean}} = \frac{A}{t_f}$$

■ Technical strain rate

$$\dot{\epsilon}(t) = \frac{d\epsilon(t)}{dt}$$

■ Technical plastic strain rate $\dot{\epsilon}_{\text{pl}} = \text{Average}\{\dot{\epsilon}(t_{R_p1}) \dots \dot{\epsilon}(t_{R_m})\}$

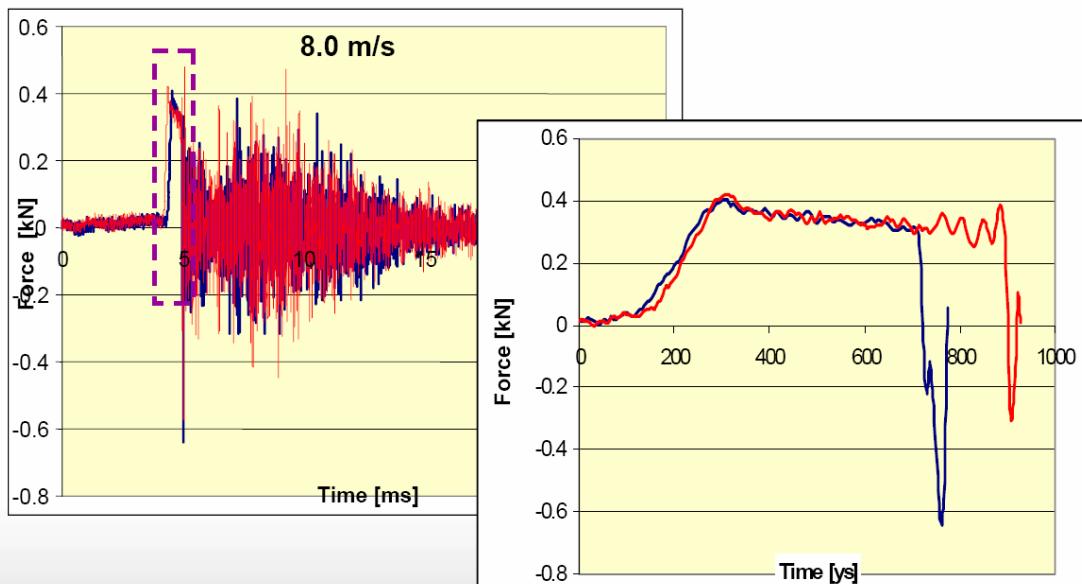
Nach Boehme, W. – IWM, Freiburg

Servohydraulic - Data Analysis



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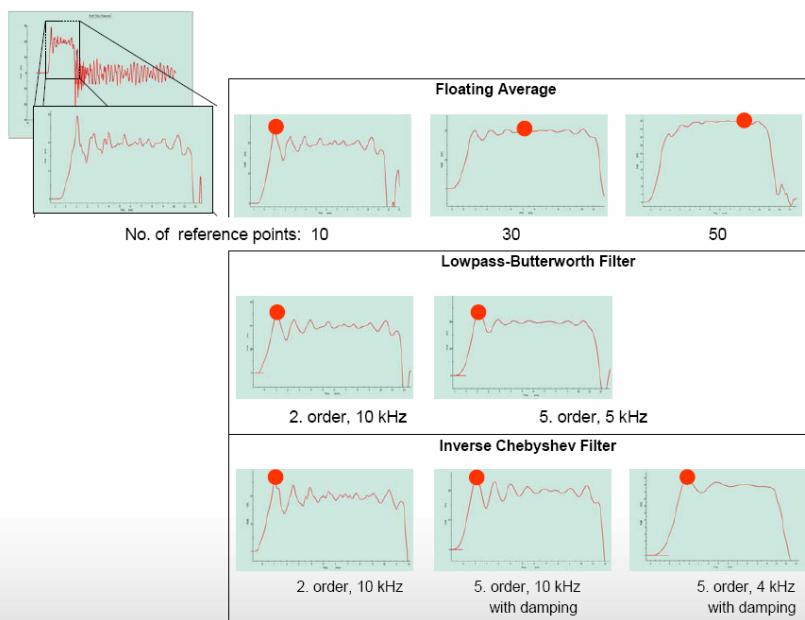
Data Analysis



Servohydraulic - Data Analysis

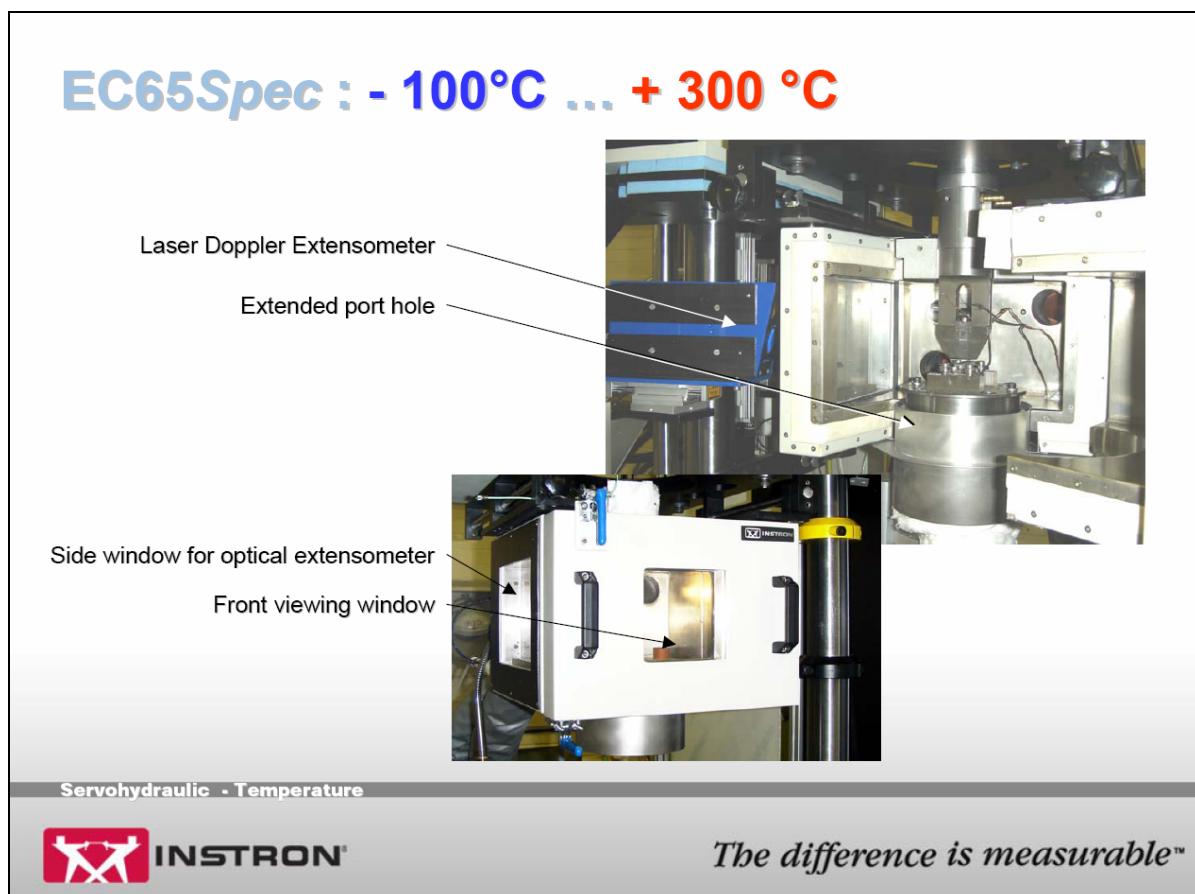
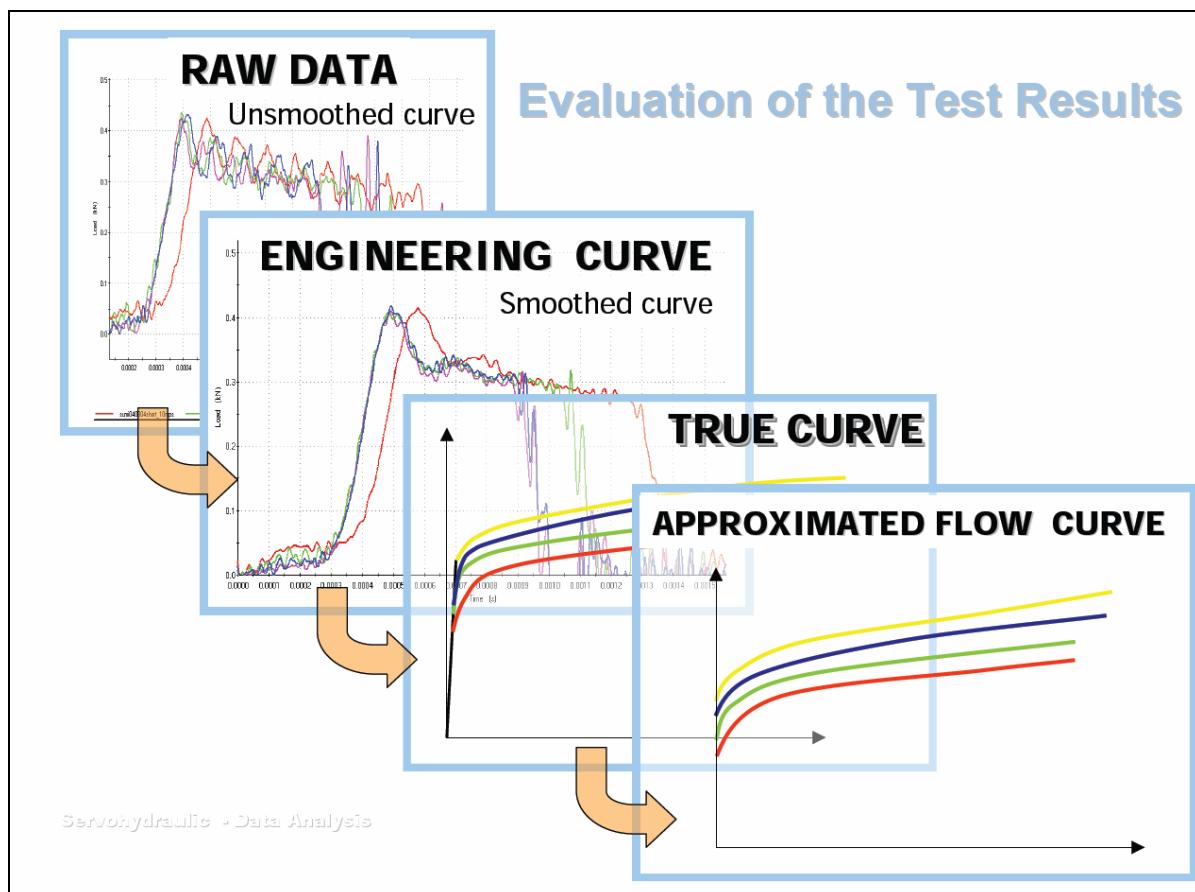
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Influence of analysis parameters



Servohydraulic - Data Analysis

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Modular Impactor System



Torso Impact



Pedestrian Impact



Catapult System



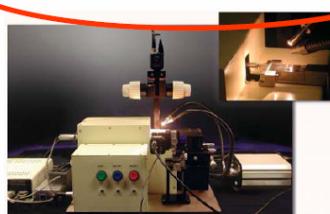
Head Impact

Servohydraulic - Impactors

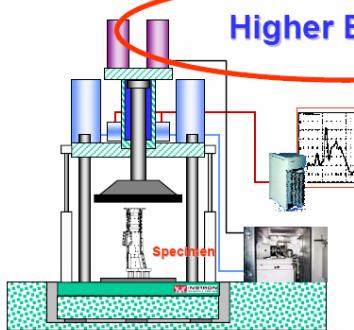
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Future Developments?

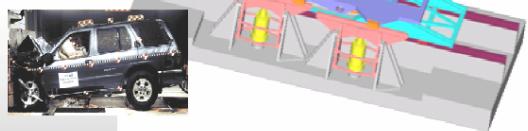
Smaller Specimens



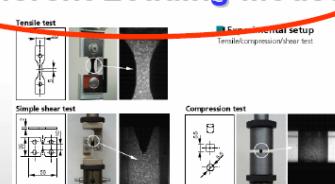
Higher Energies



Complex motion simulation under crash conditions



Different Loading Modes



Servohydraulic - New Developments



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