

Title

Development and Application of Pedestrian Protection Impactor Models

Thomas Frank – DaimlerChrysler AG, Sindelfingen

Artur Kurz – Lasso GmbH, Leinfelden

Michael Söllner – Porsche AG, Weissach

Martin Pitzer – Peng GmbH, Giessen

Keywords : Pedestrian Impactor Models, Pedestrian Protection Simulation,
LS-DYNA

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Introduction



Introduction

- During this year (2005) the first car lines have been certified according to EU-Phase I-Pedestrian-Protection legislation
- Phase II-Pedestrian-Protection legislation will be active from 2010 on; the following requirements are in discussion (ACEA-Proposal)
 - **3.5kg-Child-Headform to bonnet test**
(HPC 1000/67% - /1700/33%, WAD 1000-1700)
 - **4.5kg-Adult-Headform to bonnet test**
(HPC 1000/67% - /1700/33%, WAD > 1700)
 - **Legform to bumper test (170g/19°/6mm)**
(UpperLeg to bumper test - SUV)

Introduction

→ Compared to typical impact configurations there is a different situation for Pedestrian Protection Applications :

- System Energy less than 1000 J
- A lot of components involved are non metallic (plastics, foam)
- Not global, but local results are needed

→ Requirements for very detailed models of

- Car front structure and
- Impactor

Introduction

→ Focus in development of Pedestrian Impactor Models

- Performance in real car application
- Improvement and maintenance based on feedback of users and results of different car lines
- Impactor suite is used at DaimlerChrysler, Porsche
- This presentation is an extension of “Development and Validation of Numerical Pedestrian Impactor Models“, Th. Frank et. al. at 4th European LS-DYNA Users Conference 2003

Headform

→ Pedestrian Headform Models

- Small-Adult-Headform/Child-Headform (3.5 kg, Phase I, Phase II)
- Adult-Headform (4.5kg, EU-Phase II)
- Child-Headform (3.5kg, Japan)
- Adult-Headform (4.5kg, Japan)
- 2.5kg Child- and 4.8kg Adult-Head according to Euro-NCAP

Headform

→ Performance of Headform is mainly depending on

- Rubber Skin
- Friction (Rubber/Aluminium-Headform-Inlay and Rubber/Bonnet)

→ Rubber Skin Evaluation

- Component Tests
- Original LS-DYNA implementation => MAT_OGDEN_Rubber



Headform

→ Rubber Skin Evaluation

- Problem : Difficulty in determination of Material-Parameters according to strain energy functional :

$$W = \sum_{i=1}^3 \sum_{j=1}^n \frac{\mu_j}{\alpha_j} (\lambda_i^{\alpha_j} - 1) + \frac{1}{2} K (J-1)^2$$

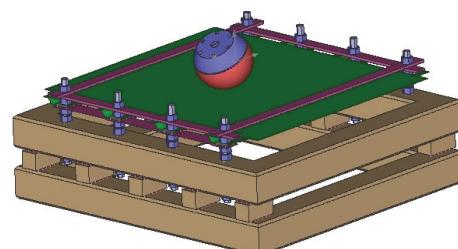
- Material-Constants μ_j, α_j can not be derived directly from test results

Headform

→ Use of MAT_SIMPLIFIED_RUBBER

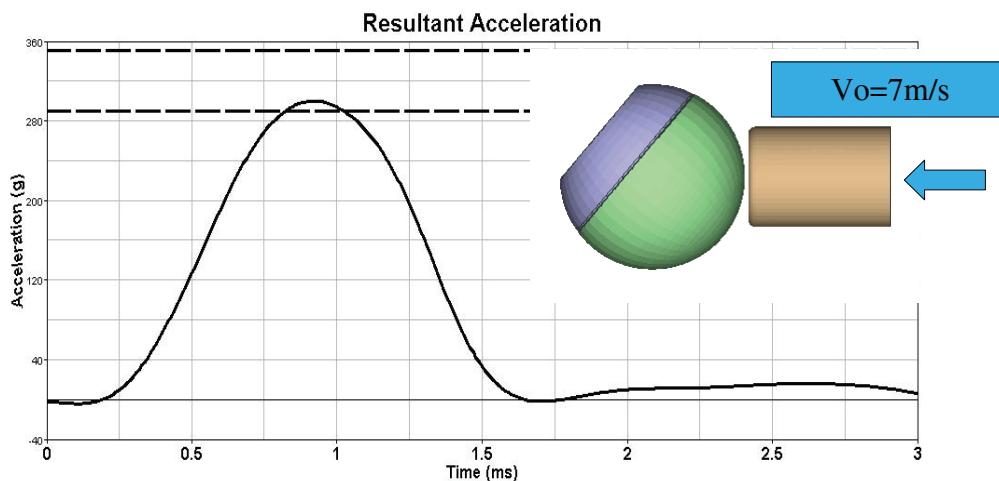
- Direct input of test results
- Table-ID accounts for strain rate effects

→ Validation of Headform Impactor has been performed with respect to test results of Headform to “Porsche-Box“



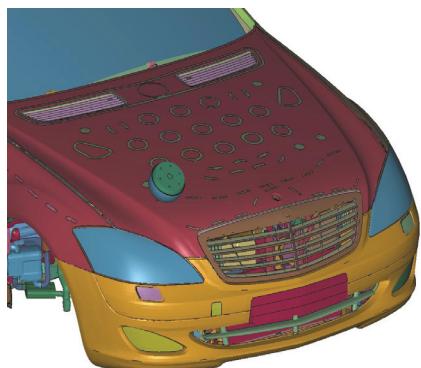
Headform

→ Small Adult-Headform – Results of Certification Test

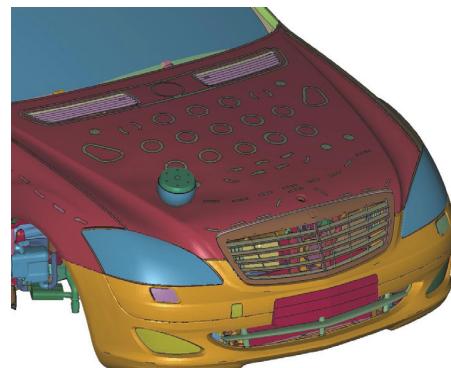


Headform

Example 1 : 3.5kg-Head-Impact (DaimlerChrysler - S-Class)

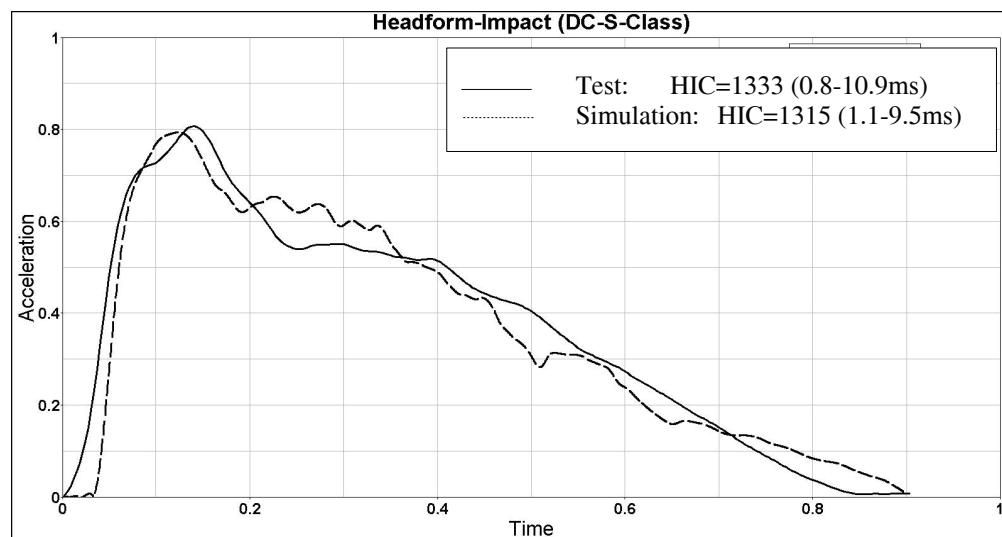


Initial Configuration



Deformed State

Headform



Legform

→ **Performance of Legform is mainly depending on**

- Confor-Foam/Neoprene-Skin
- Ligament-Stiffness
- (Shear Damper)

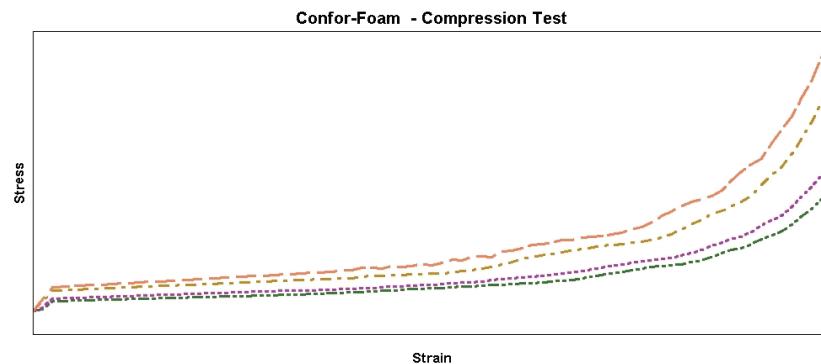


→ **Tension and compression tests at different strain rates and hydrostatic tests have been performed in order to determine the material data of Confor Foam and Neoprene-Skin**

Legform

→ Confor Foam shows dependency on

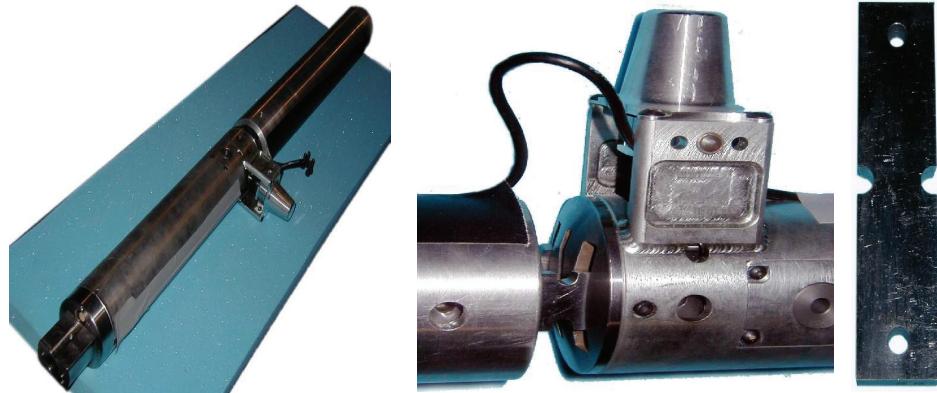
- Strain rates, Humidity, Temperature
- LS-DYNA implementation uses MAT_FU_CHANG_FOAM with Table-ID to take into account strain rate effects



Legform

→ Ligament

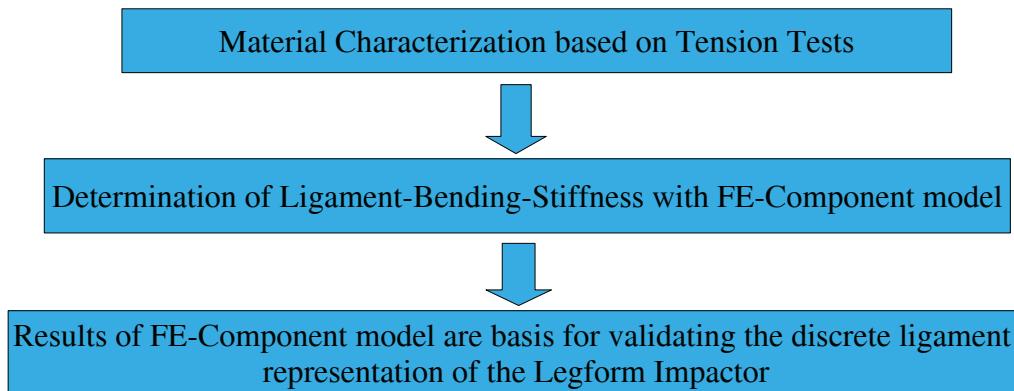
- 2 Steel-Plates (Thickness : 7mm; Notch-Diameter : 6mm)



Legform

→Ligament

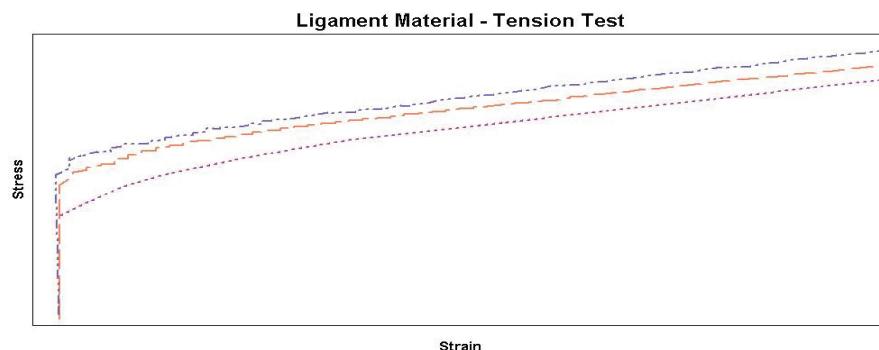
- The determination of the Ligament-Bending-Stiffness follows 3 Steps (see detailed discussion on the next slides) :



Legform

→Ligament

- Material Data has been evaluated by performing tension tests at different strain rates



- LS-DYNA MAT_PIECEWISE_LINEAR_PLASTICITY with Table-ID to account for strain rate effects

Legform

→Ligament

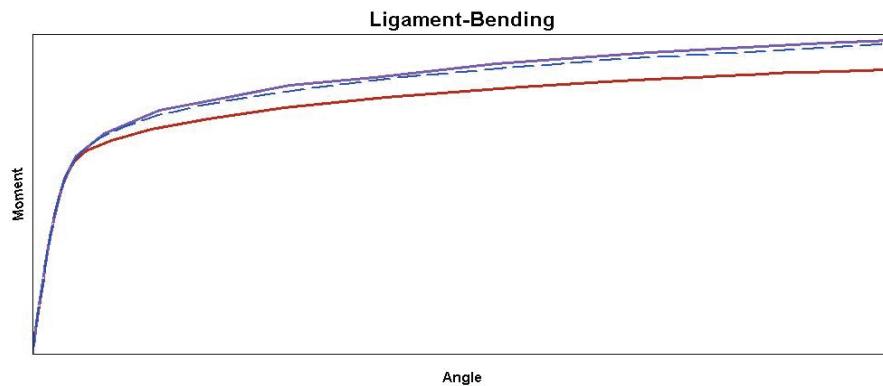
- Simulation of Ligament-Bending at different velocities using LS-DYNA (implicit) and Ligament-Material-Data from tests
- Detailed Component-Model of Ligament includes more than 10.000 Solidelements



Legform

→Ligament

- Results of component analyses characterizes the Ligament-Bending-Stiffness



Legform

→Ligament

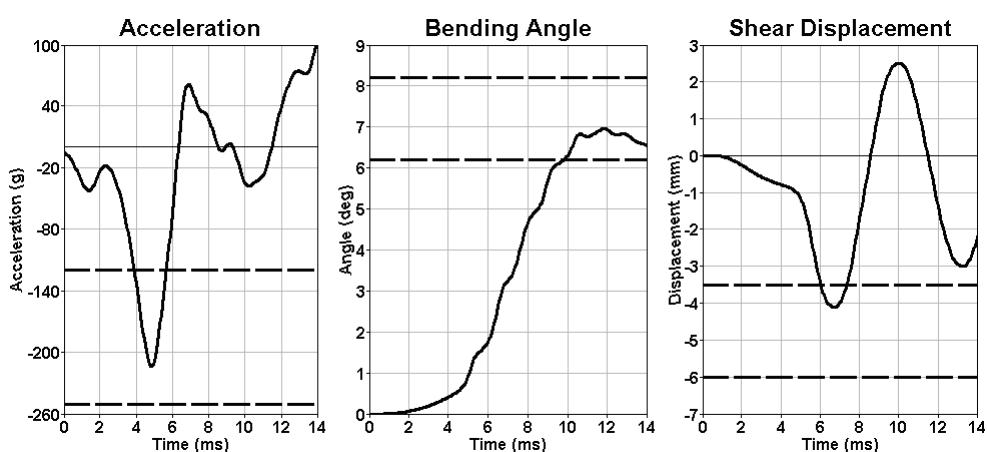
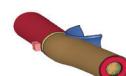
- The Ligament representation of the Legform Impactor consists of a combination of rotational spring and damper
- Results of FE-Ligament-Component-Model are used to validate spring and damper where the spring represents the quasistatic curve and the damper accounts for strain rate effects of the Ligament

→Shear-Damper

- The Damping coefficient of the Shear Damper can be found from the shear displacement versus time curves by calculating the so called logarithmic decrement

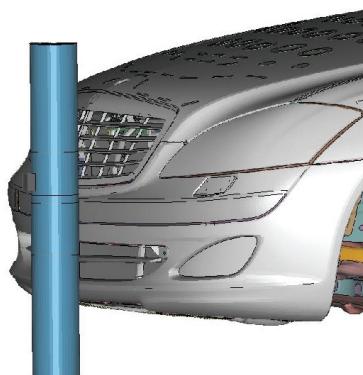
Legform

→Legform – Results of Dyn. Certification

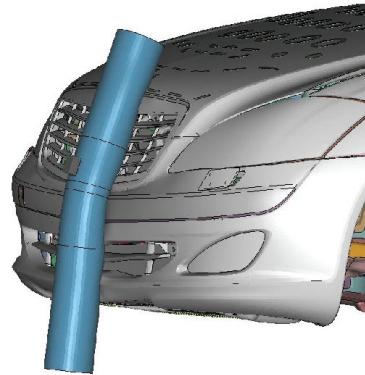


Legform

Example 2 : Legform-Impact (DaimlerChrysler - S-Class)

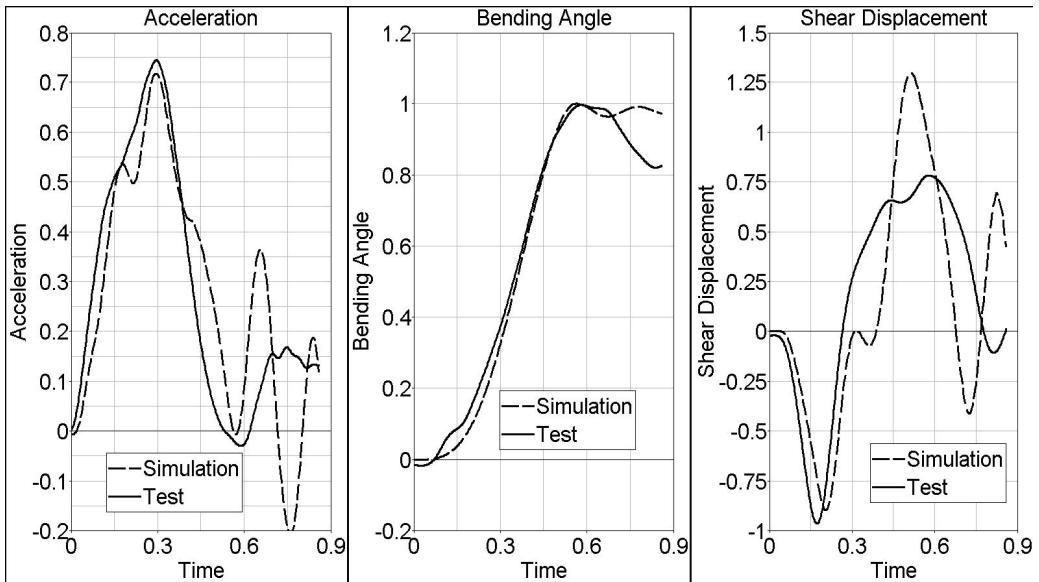


Initial Configuration



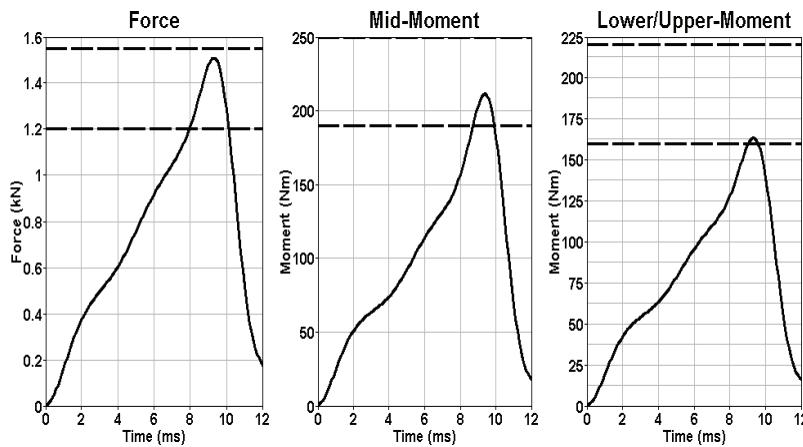
Deformed State

Legform



UpperLeg

→ UpperLeg – Results of Dynamic Certification Test



Conclusion

→ A suite of Numerical Pedestrian Impactor Models has been presented which is available to other customers

→ Main Improvements :

→ Headform-Rubber-Skin

→ Legform-Ligament

→ The development has been focused on performance in real car application

→ Maintenance and improvement will be carried out based on feedback of the users

